# **Counting Temporal Paths**

Jessica Enright<sup>1</sup> Kitty Meeks<sup>1</sup> <u>Hendrik Molter<sup>2</sup></u>

<sup>1</sup> School of Computing Science, University of Glasgow, Glasgow, UK <sup>2</sup> Department of Industrial Engineering and Management, Ben-Gurion University of the Negev, Israel

Algorithmic Aspects of Temporal Graphs V

Project initiated at Dagstuhl Seminar "Temporal Graphs: Structure, Algorithms, Applications".

#### Temporal Graph

#### Temporal Graph



#### Temporal Graph



#### Temporal Graph



#### Temporal Graph



#### Temporal Graph

A **temporal graph**  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  is a vertex set *V* with a list of edge sets  $E_1, \ldots, E_T$  over *V*, where *T* is the lifetime of  $\mathscr{G}$ .



#### Temporal (s, z)-Path

**Sequence of time edges** forming a path from *s* to *z* that have:

- increasing time stamps (strict).
- non-decreasing time stamps (non-strict).

#### Temporal Graph

A **temporal graph**  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  is a vertex set *V* with a list of edge sets  $E_1, \ldots, E_T$  over *V*, where *T* is the lifetime of  $\mathscr{G}$ .



#### Temporal (s, z)-Path

**Sequence of time edges** forming a path from *s* to *z* that have:

- increasing time stamps (strict).
- non-decreasing time stamps (non-strict).



Not a temporal path.

#### Temporal Graph

A **temporal graph**  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  is a vertex set *V* with a list of edge sets  $E_1, \ldots, E_T$  over *V*, where *T* is the lifetime of  $\mathscr{G}$ .



#### Temporal (s, z)-Path

**Sequence of time edges** forming a path from *s* to *z* that have:

- increasing time stamps (strict).
- non-decreasing time stamps (non-strict).



Not a temporal path.



Non-strict temporal path. (Not strict.)

#### Temporal Graph

A **temporal graph**  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  is a vertex set *V* with a list of edge sets  $E_1, \ldots, E_T$  over *V*, where *T* is the lifetime of  $\mathscr{G}$ .



#### Temporal (s, z)-Path

**Sequence of time edges** forming a path from *s* to *z* that have:

- increasing time stamps (strict).
- non-decreasing time stamps (non-strict).



Not a temporal path.



Non-strict temporal path. (Not strict.)



Temporal path (both strict and non-strict).

### Motivation: Temporal Betweenness



#### "How important is Berlin main station as a hub for the public transportation network?"

### Motivation: Temporal Betweenness



"How important is Berlin main station as a hub for the public transportation network?"

Betweenness of a vertex v in a graph G = (V, E):

"How likely is a shortest (optimal) path to pass through vertex v?"

Hendrik Molter, BGU

Counting Temporal Paths

Which temporal path from *s* to *z* is optimal?



Which temporal path from s to z is optimal?



**Shortest** temporal paths use the minimum number of edges.

Which temporal path from s to z is optimal?



- **Shortest** temporal paths use the minimum number of edges.
- **Foremost** temporal paths have a minimum arrival time.

Which temporal path from s to z is optimal?



- **Shortest** temporal paths use the minimum number of edges.
- **Foremost** temporal paths have a minimum arrival time.
- **Fastest** temporal paths have a minimum difference between starting and arrival time.

#### Temporal Betweenness Centrality

$$C_B^{(\star)}(v) = \sum_{s 
eq v 
eq z} egin{cases} 0 & 
eq ext{ temp.}(s,z) ext{-path} \ rac{\sigma_{sz}^{(\star)}(v)}{\sigma_{sz}^{(\star)}} & 
ext{ otherwise} \end{cases}$$

 $\sigma_{sz}^{(\star)}$ : #  $\star$ -temp. paths from s to z

 $\sigma_{sz}^{(\star)}(v)$ : #  $\star$ -temp. paths from s to z via v

#### Temporal Betweenness Centrality

$$C_{B}^{(\star)}(v) = \sum_{s 
eq v 
eq z} egin{cases} 0 & 
eq ext{ temp.}(s,z) ext{-path} \ rac{\sigma_{sz}^{(\star)}(v)}{\sigma_{sz}^{(\star)}} & ext{ otherwise} \end{cases}$$

 $\sigma_{sz}^{(\star)}$ : #  $\star$ -temp. paths from s to z  $\sigma_{sz}^{(\star)}(v)$ : #  $\star$ -temp. paths from s to z via v

\* denotes "optimality concept"

#### Temporal Betweenness Centrality

$$\mathcal{C}_{\mathcal{B}}^{(\star)}(v) = \sum_{s 
eq v 
eq z} egin{cases} 0 & 
eq ext{ temp.}(s,z) ext{-path} \ rac{\sigma_{sz}^{(\star)}(v)}{\sigma_{sz}^{(\star)}} & 
ext{ otherwise} \ \end{pmatrix}$$

 $\sigma_{sz}^{(\star)}$ : #  $\star$ -temp. paths from s to z  $\sigma_{sz}^{(\star)}(v)$ : #  $\star$ -temp. paths from s to z via v

#### \* denotes "optimality concept"

Computing temporal betweenness essentially equivalent to counting (optimal) temporal paths.

#### Temporal Betweenness Centrality

$$C^{(\star)}_{B}(v) = \sum_{s 
eq v 
eq z} egin{cases} 0 & 
eq ext{ temp.}(s,z) ext{-path} \ rac{\sigma^{(\star)}_{sz}(v)}{\sigma^{(\star)}_{sz}} & ext{ otherwise} \end{cases}$$

 $\sigma_{sz}^{(\star)}$ : #  $\star$ -temp. paths from s to z  $\sigma_{sz}^{(\star)}(v)$ : #  $\star$ -temp. paths from s to z via v

#### \* denotes "optimality concept"

- Computing temporal betweenness essentially equivalent to counting (optimal) temporal paths.
- For many interesting optimality concepts such as "foremost" or "fastest" the corresponding counting problem is **#P-hard**.

#### **#Temporal Path**

- **Input:** A temporal graph  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  and two vertices  $s, z \in V$ .
- **Task:** Count the temporal (s, z)-paths in  $\mathcal{G}$ .

#### **#Temporal Path**

**Input:** A temporal graph  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  and two vertices  $s, z \in V$ .

**Task:** Count the temporal (s, z)-paths in  $\mathcal{G}$ .

#### **Remarks:**

Solving #Temporal Path allows to count foremost temporal paths by removing all "late" time steps.

#### **#Temporal Path**

**Input:** A temporal graph  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  and two vertices  $s, z \in V$ .

**Task:** Count the temporal (s, z)-paths in  $\mathcal{G}$ .

#### **Remarks:**

- Solving #Temporal Path allows to count foremost temporal paths by removing all "late" time steps.
- Solving **#Temporal Path** allows to count **fastest** temporal paths with linear overhead (in *T*).

#### **#Temporal Path**

**Input:** A temporal graph  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  and two vertices  $s, z \in V$ .

**Task:** Count the temporal (s, z)-paths in  $\mathcal{G}$ .

#### **Remarks:**

- Solving #Temporal Path allows to count foremost temporal paths by removing all "late" time steps.
- Solving **#Temporal Path** allows to count **fastest** temporal paths with linear overhead (in *T*).
- One can count temporal (s, z)-paths via a vertex v by removing v from  $\mathscr{G}$ .

#### **#Temporal Path**

**Input:** A temporal graph  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  and two vertices  $s, z \in V$ .

**Task:** Count the temporal (s, z)-paths in  $\mathcal{G}$ .

#### **Remarks:**

- Solving #Temporal Path allows to count foremost temporal paths by removing all "late" time steps.
- Solving **#Temporal Path** allows to count **fastest** temporal paths with linear overhead (in *T*).
- One can count temporal (s, z)-paths via a vertex v by removing v from  $\mathscr{G}$ .
- For this talk: focus on **non-strict** temporal paths.

#### **#Temporal Path**

- **Input:** A temporal graph  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  and two vertices  $s, z \in V$ .
- **Task:** Count the temporal (s, z)-paths in  $\mathcal{G}$ .

#### Observation

**#Temporal Path** is **#P**-hard even if T = 1.

#### **#Temporal Path**

- **Input:** A temporal graph  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  and two vertices  $s, z \in V$ .
- **Task:** Count the temporal (s, z)-paths in  $\mathcal{G}$ .

#### Observation

**#Temporal Path** is **#P**-hard even if T = 1.

#### **Parameterized Counting**

#### **#Temporal Path**

- **Input:** A temporal graph  $\mathscr{G} = (V, (E_i)_{i \in [T]})$  and two vertices  $s, z \in V$ .
- **Task:** Count the temporal (s, z)-paths in  $\mathcal{G}$ .

#### Observation

**#Temporal Path** is **#P**-hard even if T = 1.

**Parameterized Counting** 

Approximate Counting

#### Observation

Underlying graph is forest  $\Rightarrow$  same sequence of vertices visited by any temporal (*s*,*z*)-path.

#### Observation

Underlying graph is forest  $\Rightarrow$  same sequence of vertices visited by any temporal (*s*, *z*)-path.

Let  $s = v_1, v_2, \dots, v_\ell = z$  be the sequence of vertices visited by any temporal (s, z)-path.

#### Observation

Underlying graph is forest  $\Rightarrow$  same sequence of vertices visited by any temporal (*s*, *z*)-path.

Let  $s = v_1, v_2, \dots, v_\ell = z$  be the sequence of vertices visited by any temporal (s, z)-path.

Use dynamic program F(v, t) := number of temporal (s, v)-paths that arrive in v at time t or earlier.

#### Observation

Underlying graph is forest  $\Rightarrow$  same sequence of vertices visited by any temporal (*s*, *z*)-path.

Let  $s = v_1, v_2, \dots, v_\ell = z$  be the sequence of vertices visited by any temporal (s, z)-path.

# Use dynamic program F(v,t) := number of temporal (s, v)-paths that arrive in v at time t or earlier.

$$F(v_1 = s, t) = 1$$
  

$$F(v_i, t) = \sum_{t' \le t \text{ with } \{v_{i-1}, v_i\} \in E_{t'}} F(v_{i-1}, t') \text{ for } 1 < i \le \ell.$$

#### Observation

Underlying graph is forest  $\Rightarrow$  same sequence of vertices visited by any temporal (*s*, *z*)-path.

Let  $s = v_1, v_2, \dots, v_\ell = z$  be the sequence of vertices visited by any temporal (s, z)-path.

# Use dynamic program F(v, t) := number of temporal (s, v)-paths that arrive in v at time t or earlier.

$$F(v_1 = s, t) = 1$$
  

$$F(v_i, t) = \sum_{t' \le t \text{ with } \{v_{i-1}, v_i\} \in E_{t'}} F(v_{i-1}, t') \text{ for } 1 < i \le \ell.$$

#### Theorem

#Temporal Path solvable in polynomial time if the underlying graph is a forest.

### Parameterized Hardness I

Question: How can we generalize the forest algorithm?

**Question**: How can we generalize the forest algorithm?

#### Theorem

**#Temporal Path** is  $\oplus$  W[1]-hard when parameterized by the **feedback vertex number** of the underlying graph.

**Question**: How can we generalize the forest algorithm?

#### Theorem

**#Temporal Path** is  $\oplus$  W[1]-hard when parameterized by the **feedback vertex number** of the underlying graph.

#### Main Ideas:

Jiang [TCS 2010] showed that Independent Set on 2-Track Interval Graphs is W[1]-hard when parameterized by the solution size.
**Question**: How can we generalize the forest algorithm?

## Theorem

**#Temporal Path** is  $\oplus$  W[1]-hard when parameterized by the **feedback vertex number** of the underlying graph.

## Main Ideas:

Jiang [TCS 2010] showed that Independent Set on 2-Track Interval Graphs is W[1]-hard when parameterized by the solution size.

Each vertex v represented by two intervals  $a_v, b_v$ .

Vertices v, w have an edge iff  $a_v \cap a_w \neq \emptyset$  or  $b_v \cap b_w \neq \emptyset$ .

**Question**: How can we generalize the forest algorithm?

## Theorem

**#Temporal Path** is  $\oplus$  W[1]-hard when parameterized by the **feedback vertex number** of the underlying graph.

## Main Ideas:

Jiang [TCS 2010] showed that Independent Set on 2-Track Interval Graphs is W[1]-hard when parameterized by the solution size.

Each vertex v represented by two intervals  $a_v, b_v$ .

Vertices v, w have an edge iff  $a_v \cap a_w \neq \emptyset$  or  $b_v \cap b_w \neq \emptyset$ .

Investigating the reduction shows that ⊕Multicolored Independent Set on 2-Track Interval Graphs is ⊕W[1]-hard when parameterized by the number of colors.

**Question**: How can we generalize the forest algorithm?

## Theorem

**#Temporal Path** is  $\oplus$  W[1]-hard when parameterized by the **feedback vertex number** of the underlying graph.

## Main Ideas:

Jiang [TCS 2010] showed that Independent Set on 2-Track Interval Graphs is W[1]-hard when parameterized by the solution size.

Each vertex v represented by two intervals  $a_v, b_v$ .

Vertices v, w have an edge iff  $a_v \cap a_w \neq \emptyset$  or  $b_v \cap b_w \neq \emptyset$ .

- Investigating the reduction shows that ⊕Multicolored Independent Set on 2-Track Interval Graphs is ⊕W[1]-hard when parameterized by the number of colors.
- Model one track with vertices and one with time.















**Problem**: "Cheating" temporal paths.

**Problem**: "Cheating" temporal paths.

Problem: "Cheating" temporal paths.



Problem: "Cheating" temporal paths.



Problem: "Cheating" temporal paths.



Problem: "Cheating" temporal paths.



Problem: "Cheating" temporal paths.

Idea: There should always be an even number of cheating temporal (s, z)-paths.



## Lemma

The parity of temporal (s, z)-paths equals the parity of **colorful** independent sets.

# Generalizations of the Forest Algorithm and Further Results

#### Theorem

**#Temporal Path** is in FPT when parameterized by the **feedback edge number** of the underlying graph.

# Generalizations of the Forest Algorithm and Further Results

#### Theorem

**#Temporal Path** is in FPT when parameterized by the **feedback edge number** of the underlying graph.

#### Theorem

#Temporal Path is in FPT when parameterized by the timed feedback vertex number.

# Generalizations of the Forest Algorithm and Further Results

#### Theorem

**#Temporal Path** is in FPT when parameterized by the **feedback edge number** of the underlying graph.

#### Theorem

#Temporal Path is in FPT when parameterized by the timed feedback vertex number.

## Theorem

**#Temporal Path** is in FPT when parameterized by the **treewidth** of the underlying graph and the **lifetime** *T*.

#### Theorem

#Temporal Path is in FPT when parameterized by the vertex-interval-membership-width.

## Timed Feedback Vertex Set

Minimum size  $X \subseteq V \times [T]$  such that underlying graph of  $\mathscr{G} - X$  is a forest.



## Timed Feedback Vertex Set

Minimum size  $X \subseteq V \times [T]$  such that underlying graph of  $\mathscr{G} - X$  is a forest.



Go through all variants which (and in which order) to traverse TFVS appearances.

## Timed Feedback Vertex Set

Minimum size  $X \subseteq V \times [T]$  such that underlying graph of  $\mathscr{G} - X$  is a forest.



Go through all variants which (and in which order) to traverse TFVS appearances.

## Timed Feedback Vertex Set

Minimum size  $X \subseteq V \times [T]$  such that underlying graph of  $\mathscr{G} - X$  is a forest.



Go through all variants which (and in which order) to traverse TFVS appearances.

Use forest algorithm to compute all ways to close "gaps" between TFVS appearances.

## Timed Feedback Vertex Set

Minimum size  $X \subseteq V \times [T]$  such that underlying graph of  $\mathscr{G} - X$  is a forest.



- Go through all variants which (and in which order) to traverse TFVS appearances.
- Use forest algorithm to compute all ways to close "gaps" between TFVS appearances.
- For every valid way to glue together a temporal (*s*, *z*)-path, the number of temporal (*s*, *z*)-paths visiting the same vertex sequence equals the **product** of the number of ways to close each gap.





Note: Intersection graphs of paths segments in forests are chordal.



Note: Intersection graphs of paths segments in forests are chordal.

## #Weighted Multicolored Independent Set on Chordal Graphs

**Input:** A chordal graph G = (V, E), a coloring  $c : V \to [k]$ , and weights  $w : V \to \mathbb{N}$ .

**Task:** Compute  $\sum_{X \subseteq V | X \text{ is a multicolored independent set in } G \prod_{v \in X} w(v)$ .



Note: Intersection graphs of paths segments in forests are chordal.

## #Weighted Multicolored Independent Set on Chordal Graphs

**Input:** A chordal graph G = (V, E), a coloring  $c : V \to [k]$ , and weights  $w : V \to \mathbb{N}$ .

**Task:** Compute  $\sum_{X \subseteq V | X \text{ is a multicolored independent set in } G \prod_{v \in X} w(v)$ .

# Idea: Adapt FPT algorithm for Multicolored Independent Set on Chordal Graphs parameterized by number of colors by Bentert, van Bevern, and Niedermeier [JOSH 2019].

Hendrik Molter, BGU

# Approximation Results

## Theorem

There is no FPRAS for **#Temporal Path** unless NP=BPP.

## Theorem

There is no FPRAS for **#Temporal Path** unless NP=BPP.

#### Theorem

**#Temporal Path** admits an FPTRAS when parameterized by the maximum length of a temporal (s, z)-path.

## Theorem

There is no FPRAS for **#Temporal Path** unless NP=BPP.

#### Theorem

**#Temporal Path** admits an FPTRAS when parameterized by the maximum length of a temporal (s, z)-path.

## Problems:

Not straightforward to approximate number of temporal (s, z)-path that visit a vertex v.

#### Theorem

There is no FPRAS for **#Temporal Path** unless NP=BPP.

#### Theorem

**#Temporal Path** admits an FPTRAS when parameterized by the maximum length of a temporal (s, z)-path.

## Problems:

- Not straightforward to approximate number of temporal (s, z)-path that visit a vertex v.
- Not straightforward to approximate temporal betweenness.

## Summary:

To the best of our knowledge we initiated exploring the parameterized and approximation complexity landscape of temporal path counting.

## Summary:

- To the best of our knowledge we initiated exploring the parameterized and approximation complexity landscape of temporal path counting.
- Solvable in polynomial time if underlying graph is a forest.

## Summary:

- To the best of our knowledge we initiated exploring the parameterized and approximation complexity landscape of temporal path counting.
- Solvable in polynomial time if underlying graph is a forest.
- Presumably not in FPT for the feedback vertex number of the underlying graph.

## Summary:

- To the best of our knowledge we initiated exploring the parameterized and approximation complexity landscape of temporal path counting.
- Solvable in polynomial time if underlying graph is a forest.
- Presumably not in FPT for the feedback vertex number of the underlying graph.
- FPT algorithms for several "distance to forest"-parameterizations.
## Conclusion and Future Research

### Summary:

- To the best of our knowledge we initiated exploring the parameterized and approximation complexity landscape of temporal path counting.
- Solvable in polynomial time if underlying graph is a forest.
- Presumably not in FPT for the feedback vertex number of the underlying graph.
- FPT algorithms for several "distance to forest"-parameterizations.

## Future Work:

Investigate vertex cover number of the underlying graph as a parameter.

## Conclusion and Future Research

### Summary:

- To the best of our knowledge we initiated exploring the parameterized and approximation complexity landscape of temporal path counting.
- Solvable in polynomial time if underlying graph is a forest.
- Presumably not in FPT for the feedback vertex number of the underlying graph.
- FPT algorithms for several "distance to forest"-parameterizations.

## **Future Work:**

- Investigate vertex cover number of the underlying graph as a parameter.
- Most results seem also to work for restless temporal paths or delay-robust routes.

## Conclusion and Future Research

### Summary:

- To the best of our knowledge we initiated exploring the parameterized and approximation complexity landscape of temporal path counting.
- Solvable in polynomial time if underlying graph is a forest.
- Presumably not in FPT for the feedback vertex number of the underlying graph.
- FPT algorithms for several "distance to forest"-parameterizations.

### **Future Work:**

- Investigate vertex cover number of the underlying graph as a parameter.
- Most results seem also to work for restless temporal paths or delay-robust routes.



Link to arXiv.

# Thank you!