Approximating Multistage Matching Problems

and other subgraph problems

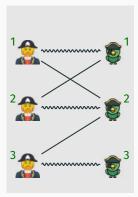
Markus Chimani joint work with Niklas Troost and Tilo Wiedera

"Approximating Multistage Matching Problems." IWOCA 2021.

"A General Approach to Approximate Multistage Subgraph Problems."

arXiv 2107.02581.





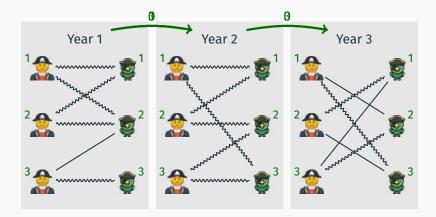
Given: Compatibility graph.Task: Find a unique compatible parrot for each pirate.

Definition (Perfect Matching)

A perfect matching in a graph G = (V, E) is a set $M \subseteq E$ of edges, such that

- no two edges in M share an endpoint,
- each vertex in V is incident with an edge in M.

Motivation: Multistage Perfect Matching

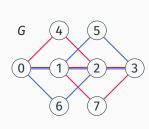


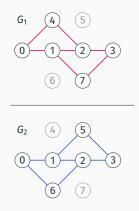
Task: Find a perfect matching in each year such that the sum of common edges in consecutive years is maximized.

Formal setting

Definition

- ► A multistage graph is a tuple $G = (V, E_1, ..., E_\tau)$ consisting of a set of vertices V and multiple sets of edges $E_i \subseteq \binom{V}{2}$.
- The graph induced by some E_i is called the *i*-th stage of G and denoted G_i.



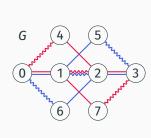


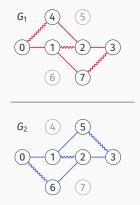
Formal setting

Definition

► A multistage perfect matching in *G* is a sequence of matchings $\mathcal{M} = (M_i)_{i=1}^{\tau}$ such that each M_i is a perfect matching in G_i . The profit of \mathcal{M} is $p(\mathcal{M}) := \sum_{i=1}^{\tau-1} |M_i \cap M_{i+1}|$.

• MIM is the problem of finding an M that maximizes p(M).





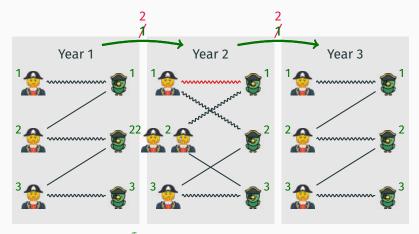
► Deciding MIM is NP-hard...

...for \geq 6 stages [Gupta et al. 2014], ...for \geq 2 stages [Bampis et al. 2018], ...for \geq 2 stages & each stage consists only of disjoint cycles

Maximum Multistage Matching (with edge weights) is APX-hard, but there is a 1/2-approximation [Bampis et al. 2018].
Task: Maximize p(M)+∑_{i=1}^τ w(M_i).

Doesn't this include our problem?

Multistage PerfectPerfect Matching



$$p(\mathcal{M}) + \sum_{i=1}^{\tau} w(M_i) = (1+1) + (3+3+3) = 11$$
$$p(\mathcal{M}') + \sum_{i=1}^{\tau} w(M'_i) = (2+2) + (3+2+3) = 12$$
_{6/14}

Approximation under hard constraints

for each stage

Perfect Matching is preficient (=preference efficient)

Given: Graph G = (V, E), edge set $P \subseteq E$.

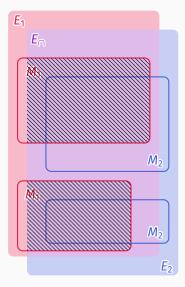
Task: Compute a perfect matching *M* on *G* that maximizes $|M \cap P|$.

prefPM(G, F)

foreach $e \in E \setminus P$ do $| w(e) \leftarrow 1$ foreach $e \in P$ do $| w(e) \leftarrow 1 + \varepsilon$ compute a maximum weight matching *M* on *G* return *M*

2IM-Approx

$$\begin{split} P \leftarrow E_{\cap} \\ \textbf{while} \ |P| &> 0 \ \textbf{do} \\ & \left| \begin{array}{c} M_{1} \leftarrow \text{prefPM}(G_{1}, P) \\ M_{2} \leftarrow \text{prefPM}(G_{2}, M_{1}) \\ P \leftarrow P \setminus M_{1} \end{array} \right. \\ \textbf{return that} \ (M_{1}, M_{2}) \ \textit{from above} \\ \text{with maximal } p(M_{1}, M_{2}) \end{split}$$



Approximation for two stages: Proof sketch

Theorem

2IM-Approx is a (tight) $1/\sqrt{2\chi}$ -approximation.

Proof sketch.

Let $M^*_{\cap} = M^*_1 \cap M^*_2$ be optimal. Assume $p(M^*_1, M^*_2) = |M^*_{\cap}| \ge 1$.

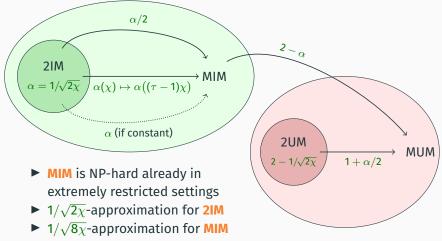
Case 1: $|M_{\cap}^*| \le \sqrt{2\chi}$ is "small". \Rightarrow Any solution with profit $|M_1 \cap M_2| \ge 1$ suffices.

Case 2: $|M^*_{\cap}| > \sqrt{2\chi}$ is "large".

▶ Suppose in each iteration only "few" edges in $M_1 \cap M_{\cap}^* \cap P$.

- ⇒ We need "many" iterations, but the number of remaining edges in $M^*_{\cap} \cap P$ decreases "slowly".
- \Rightarrow **M**₁ prefers **M**^{*}_{\cap \beta} \cap **P**.
- ⇒ Eventually, $M_1 \cap M^*_{\cap} \cap P$ is "large". \checkmark
- M_2 maximizes $|M_1 \cap M_2| \ge |M_1 \cap M_2^*|$.

Further results for matchings



- natural ILP for 2IM has LP-gap of $\sqrt{\chi}$
- If MIM is APX-hard, so is 2IM
- Approx. algorithms for MUM (=minimize unions)

Subgraph Problem (SP): [Intuition] Given a graph, find a subset of its graph elements that optimizes some measure.

Examples: Matching, Shortest Path, Vertex Cover, Independent Set, Max. Planar Subgraph,...

Multistage Subgraph Problem (MSP): [Intuition] Given an SP, find **optimal** solutions for each stage. **Maximize** transition profit.

Theorem

Consider a **preficient** MSP where we maximize the intersection between consecutive stages. On two stages, it allows a $1/\sqrt{2|\chi|}$ -approximation. On arbitrarily many stages, it allows a $1/\sqrt{8|\chi|}$ -approximation.

Preficiency?

Theorem

Consider a **preficient** MSP where we maximize the intersection between consecutive stages. On two stages, it allows a $1/\sqrt{2|\chi|}$ -approximation. On arbitrarily many stages, it allows a $1/\sqrt{8|\chi|}$ -approximation.

Preficient MSP: underlying SP allows a polynomial algorithm that prefers some graph elements over others.

Preficiency is typically trivial to show

(add some small $\varepsilon >$ 0 to cost function)

- \implies Theorem applicable to, e.g., the NP-hard multistage versions of:
 - Shortest s-t-path, Minimum s-t-cut, Maximum s-t-cut on weakly-bipartite graphs (superset of planar graphs),
 Minimum-Weight Vertex Cover on bipartite graphs,
 Maximum-Weight Independent Set on bipartite graphs,...

Core question in all our investigations:

How well can be approximate a multistage problem if we require **optimal** solutions in each stage.

Open questions:

- We always end up with approximation ratios $\Theta(1/\sqrt{\chi})$. Is this best-possible for general MSPs? For matchings?
- What about optimal transitions but suboptimal per-stage solutions?

Thank you!