

# Optimizing Reachability Sets in Temporal Graphs by Delaying

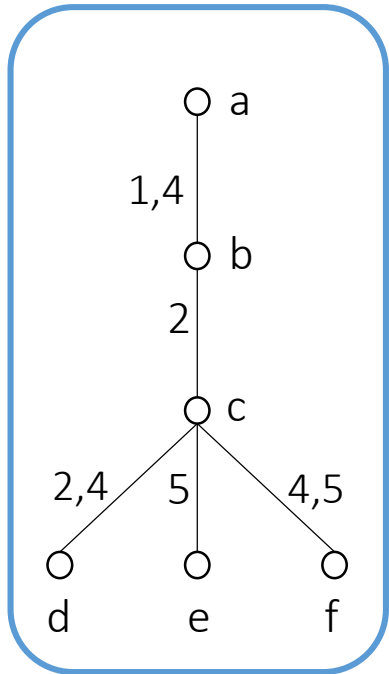
**Argyrios Deligkas, Igor Potapov**

Algorithmic Aspects of Temporal Graphs II

ICALP 2019

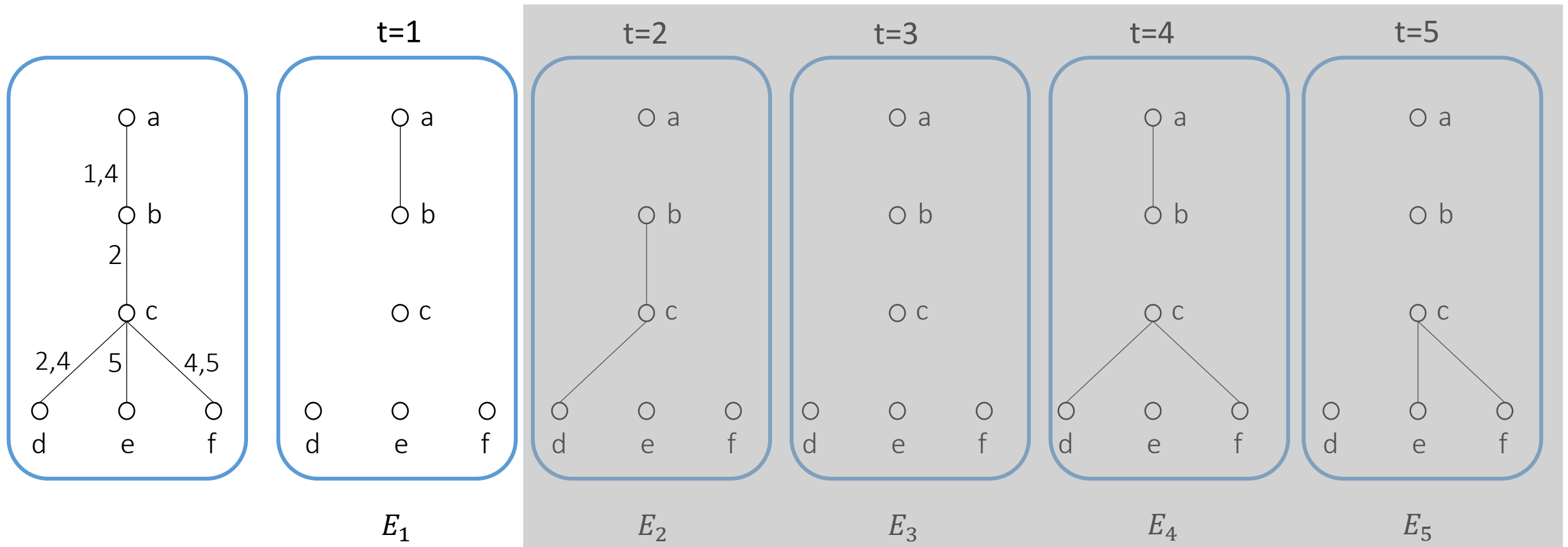
# Temporal Graphs

- Graph  $G = (V, E)$
- Labelling function  $T$



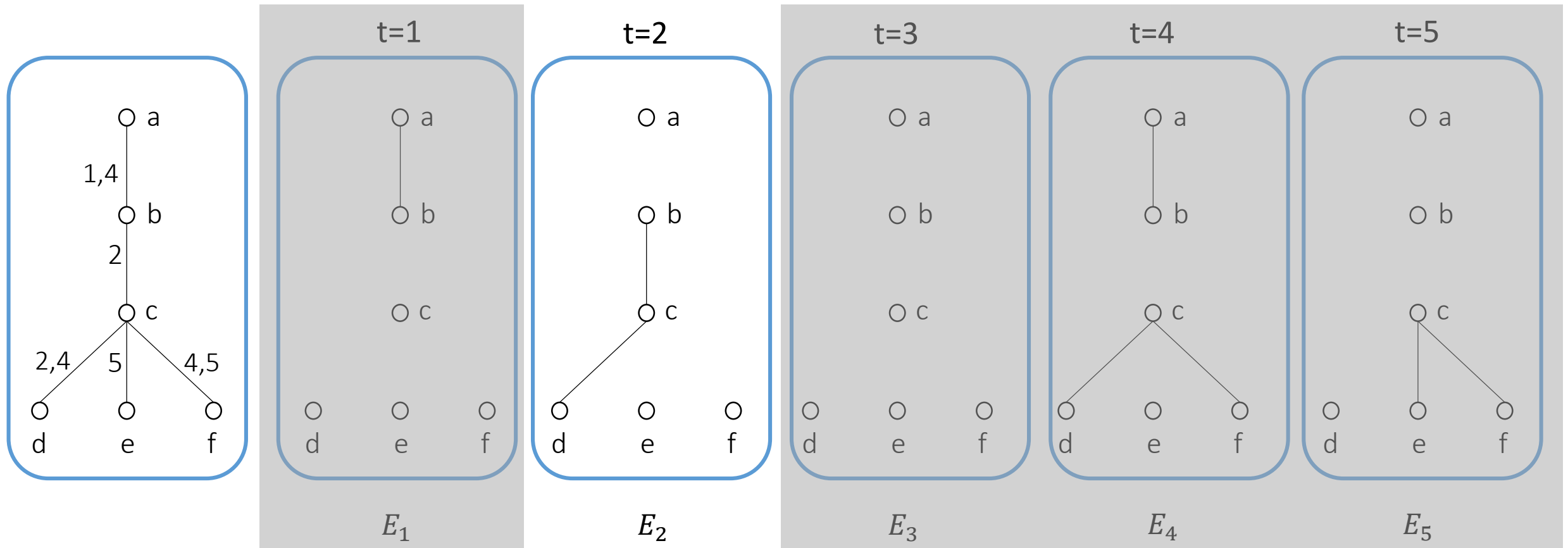
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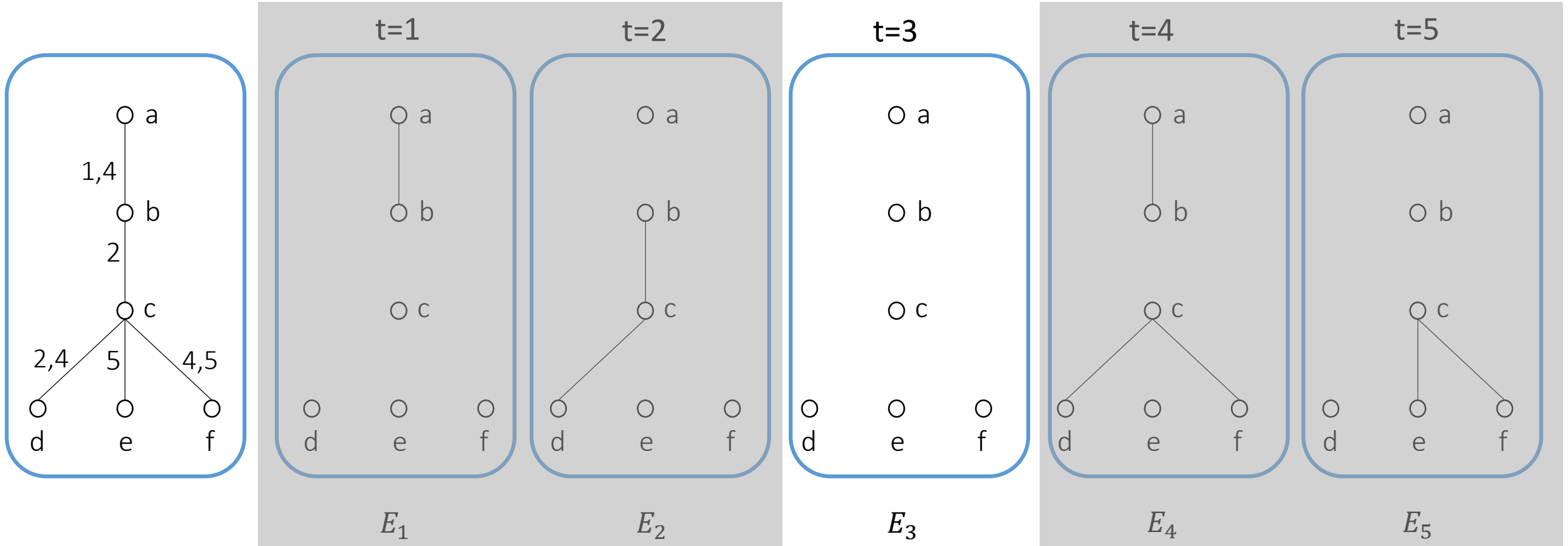
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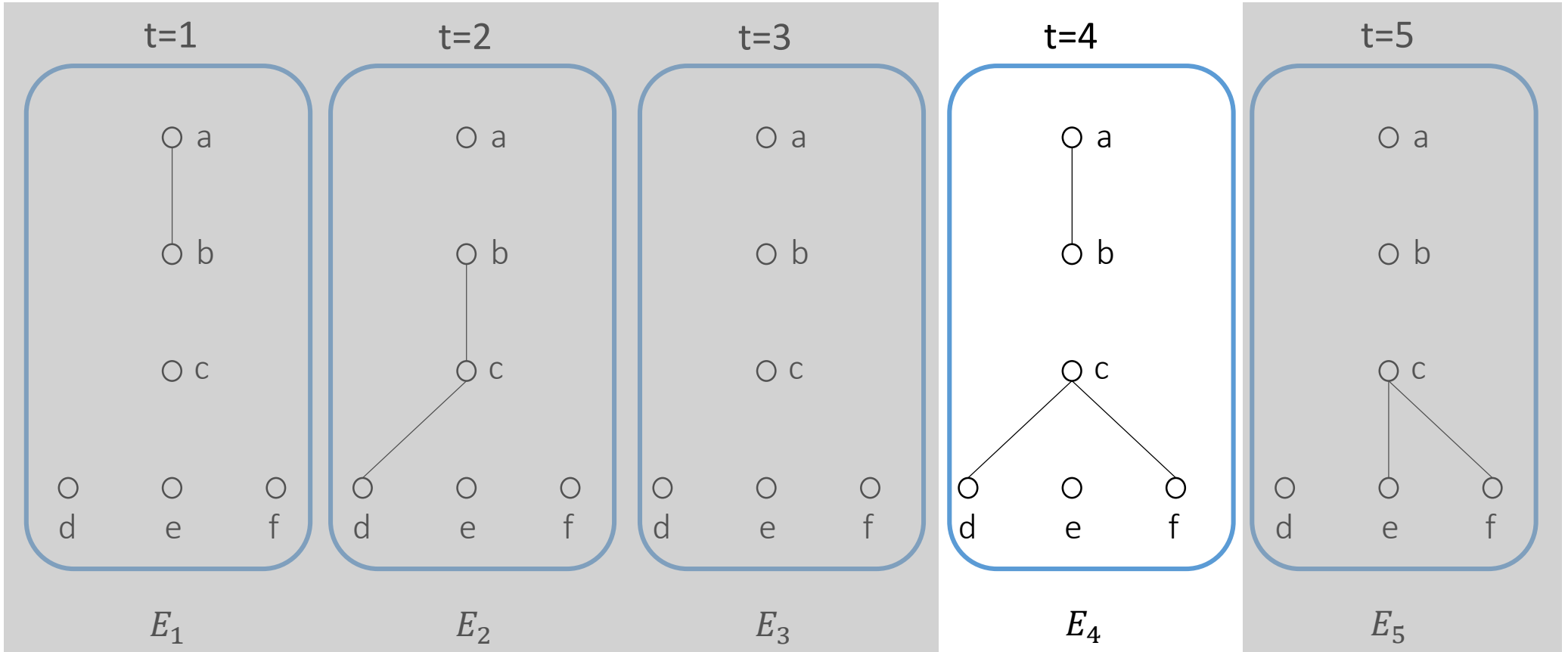
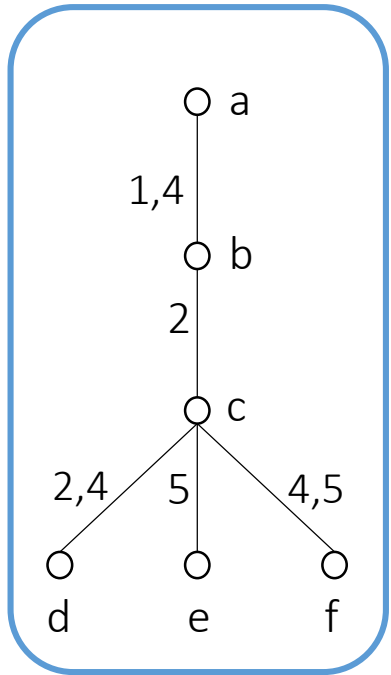
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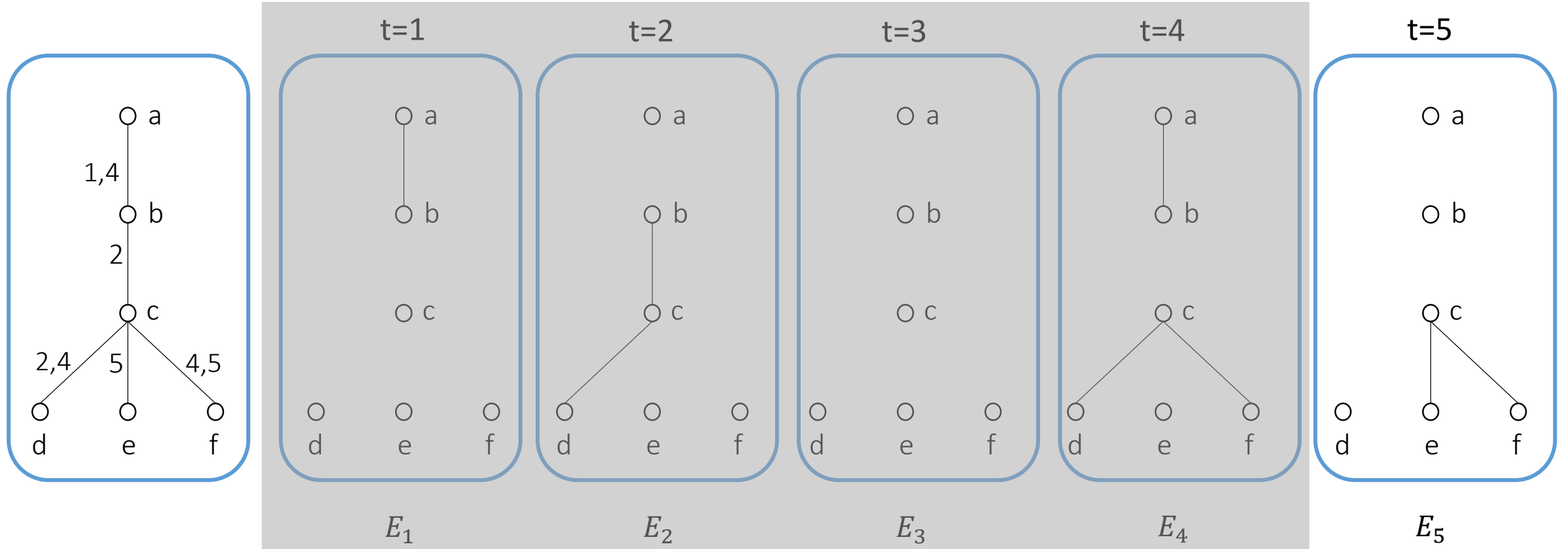
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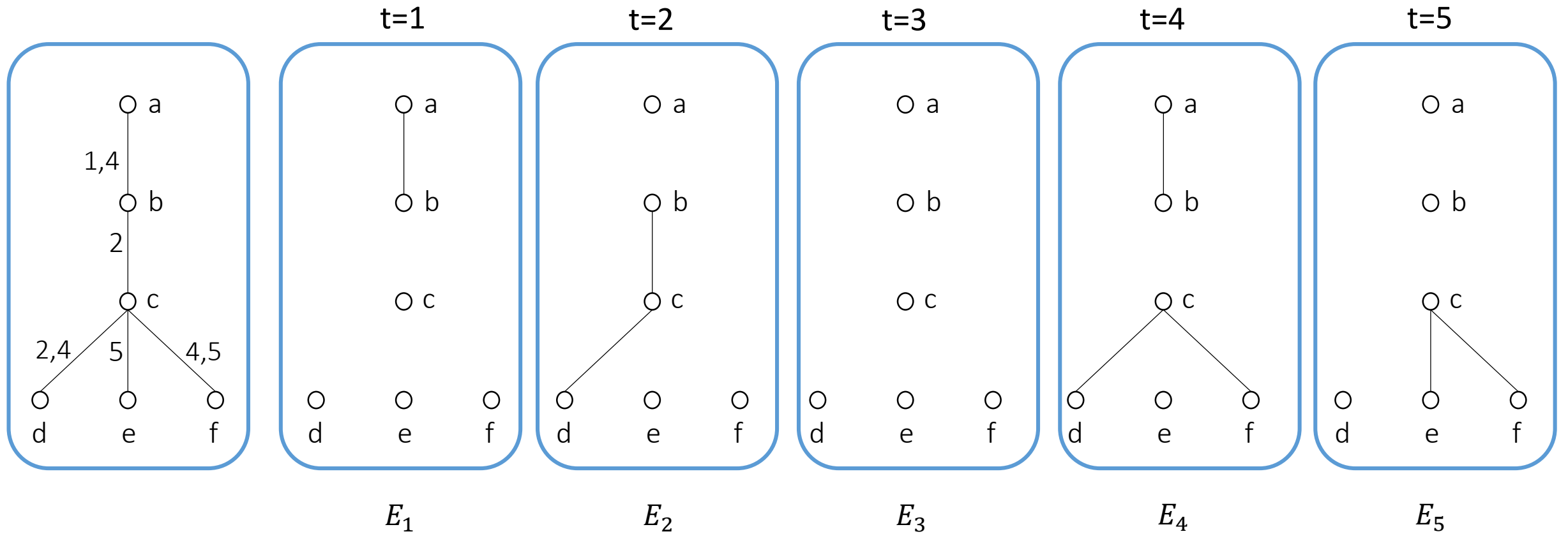
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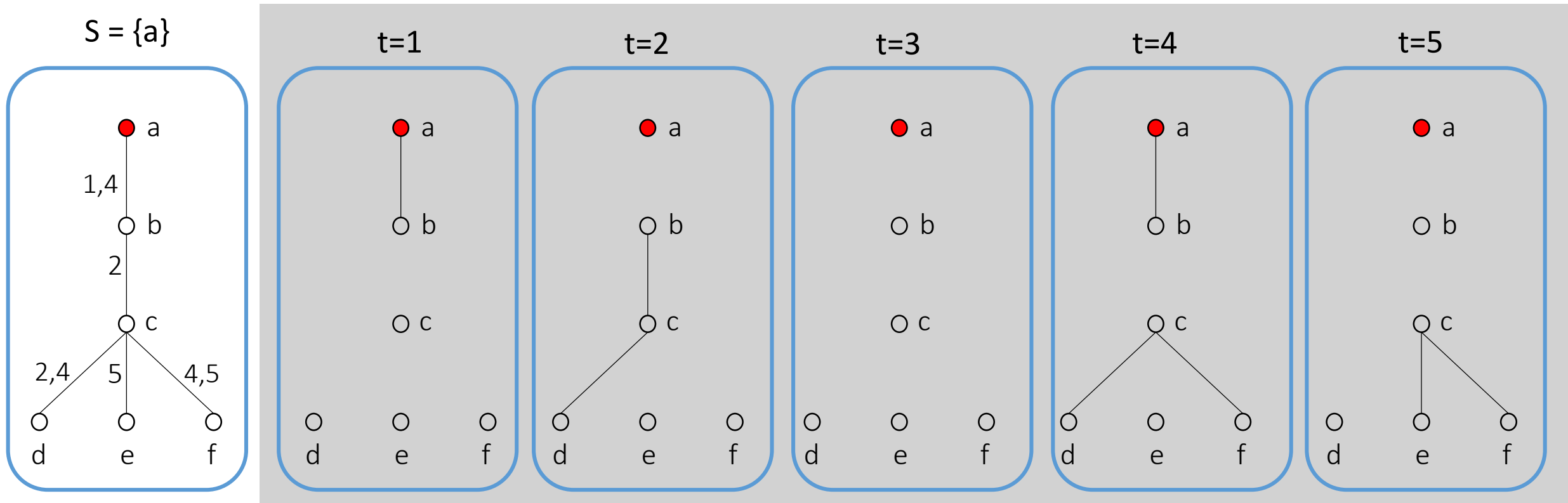
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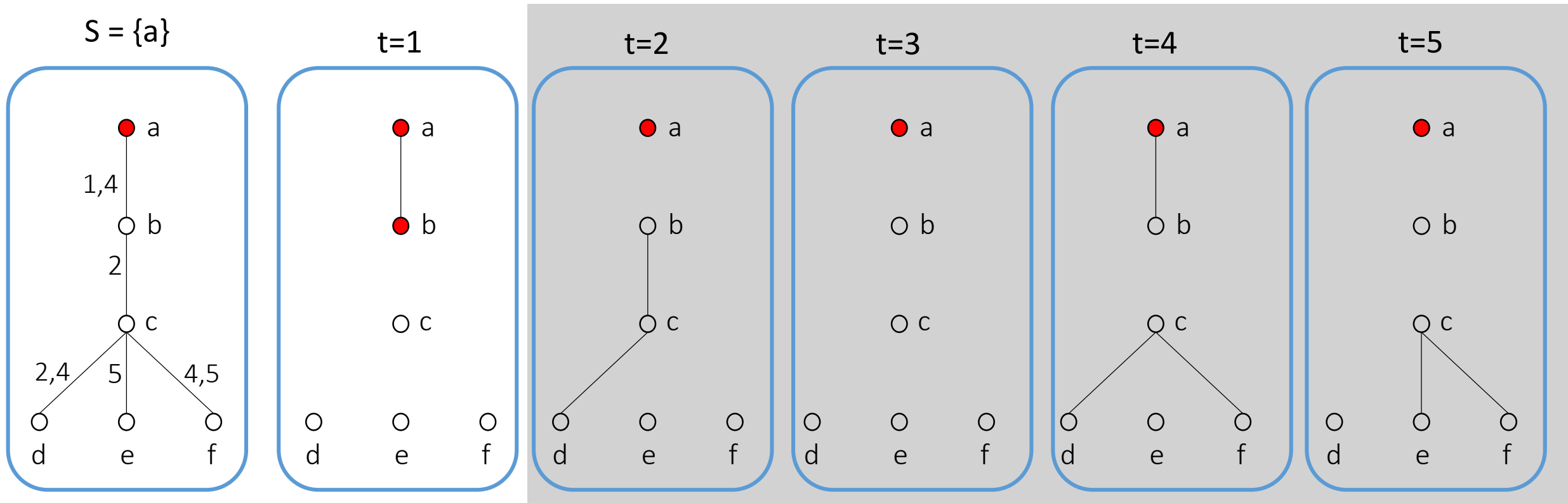
# Reachability sets in temporal graphs

- Graph  $G = (V, E)$
- Labelling function  $T$
- Set of sources  $S$



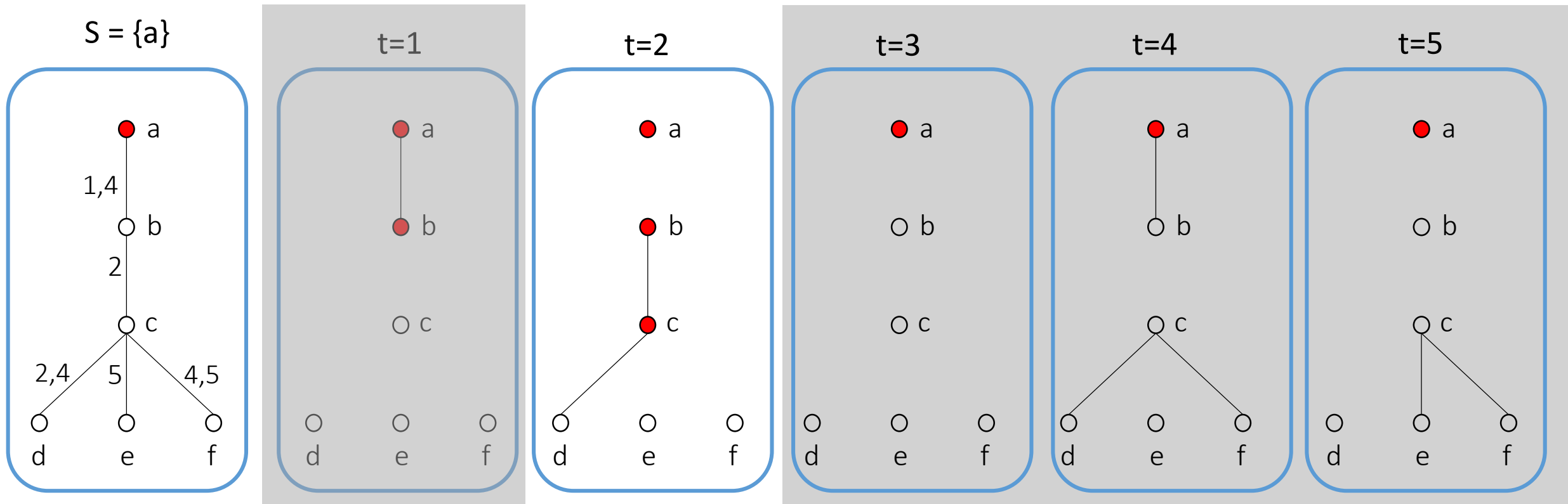
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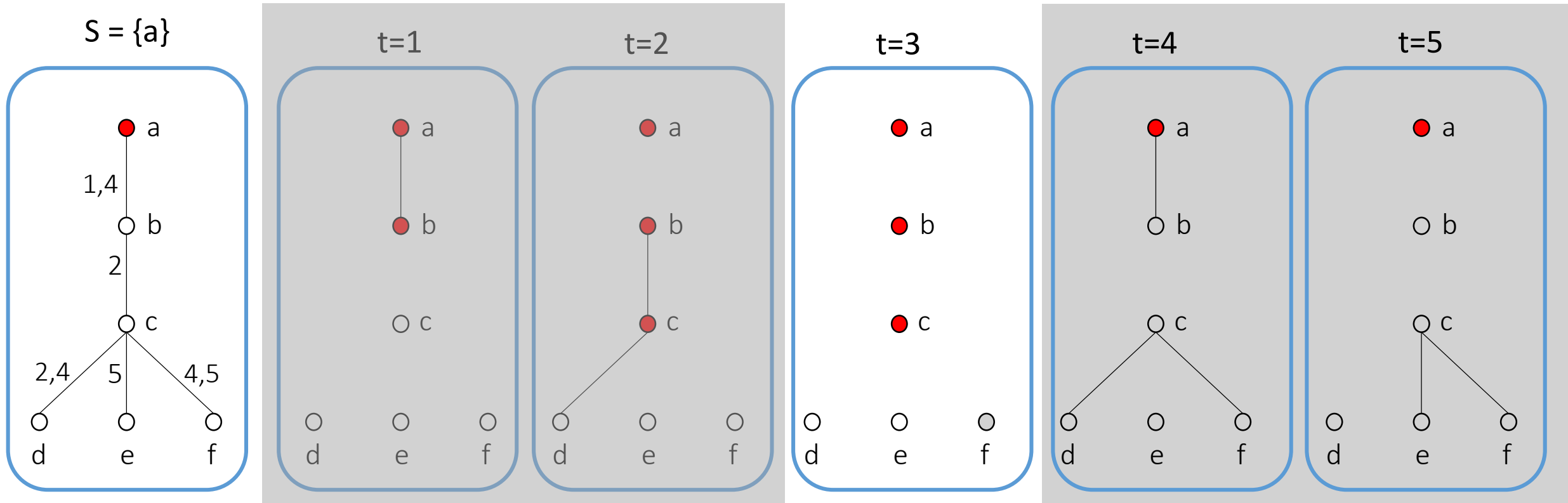
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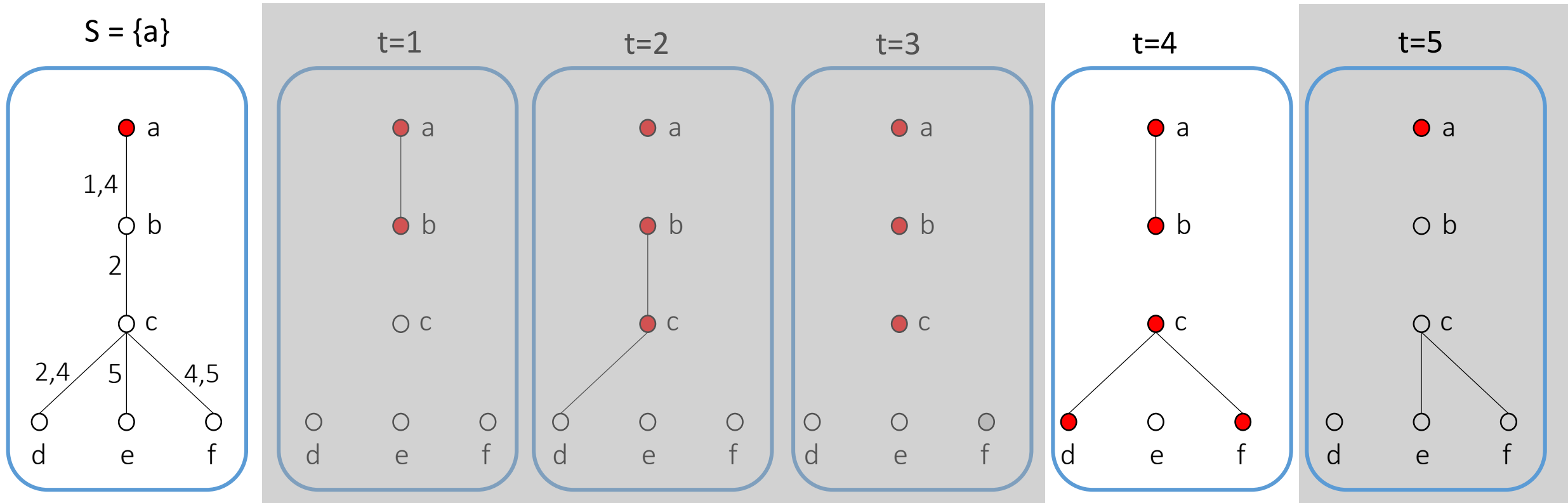
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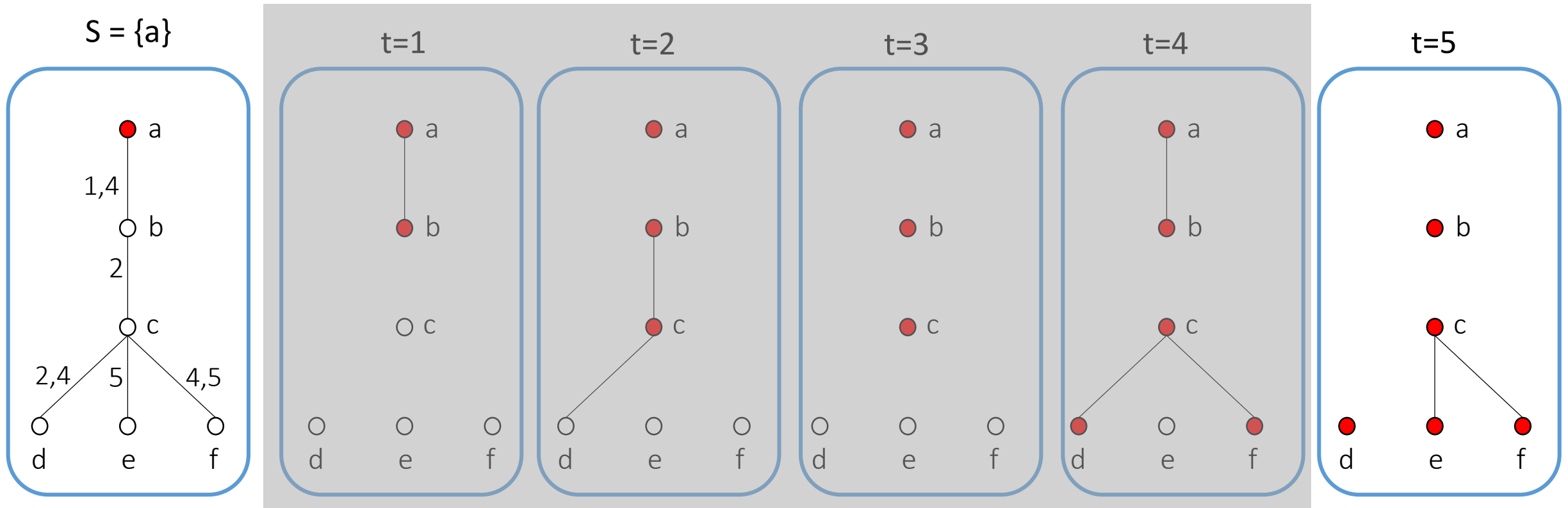
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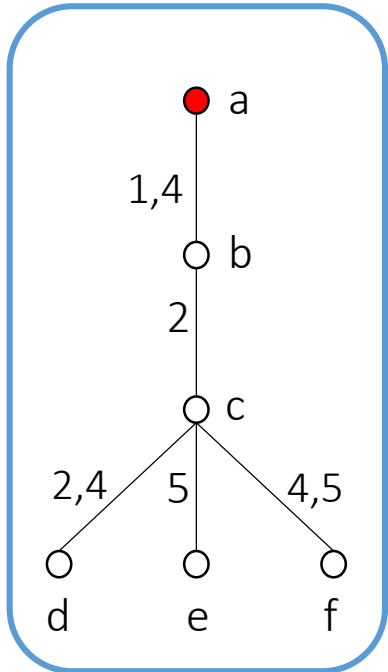
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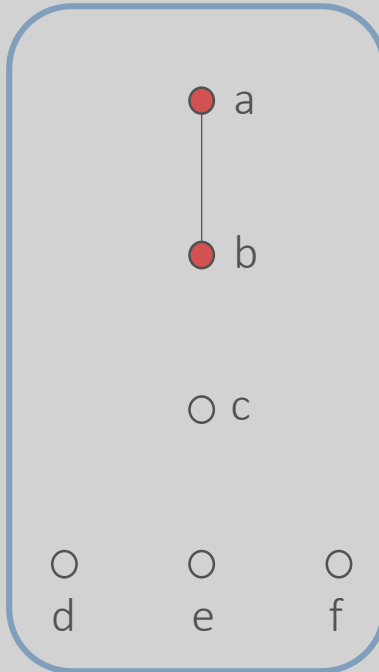
$reach(v, \langle G, T \rangle)$

Reachability set of  $v$ : Set of reachable vertices from  $v$

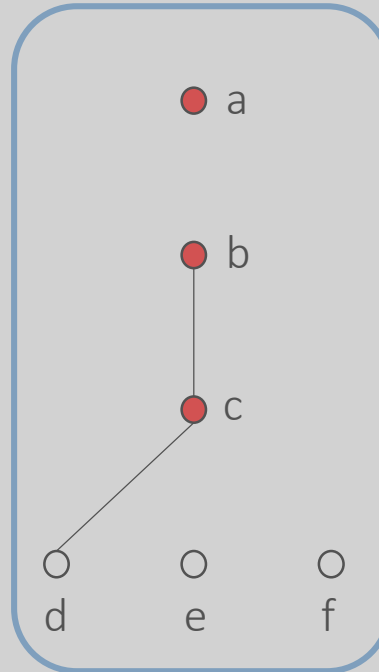
$S = \{a\}$



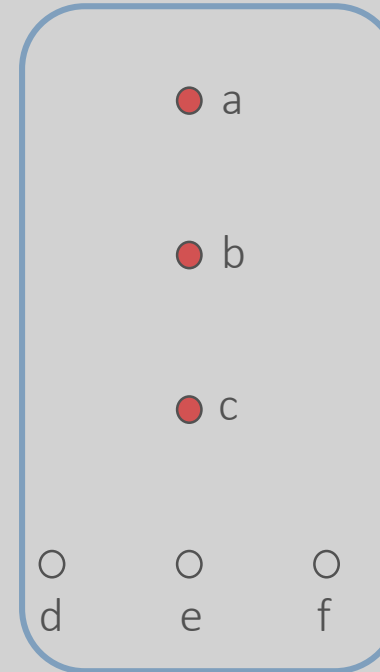
$t=1$



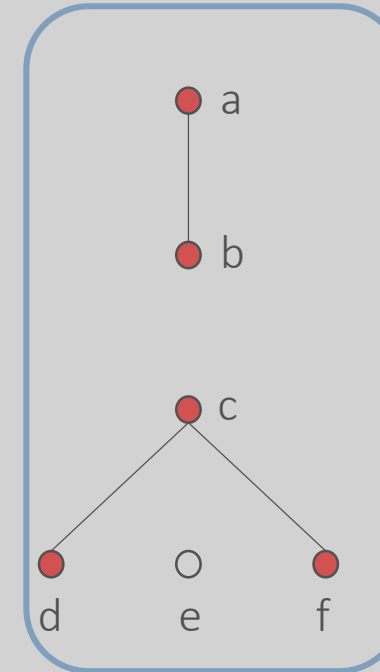
$t=2$



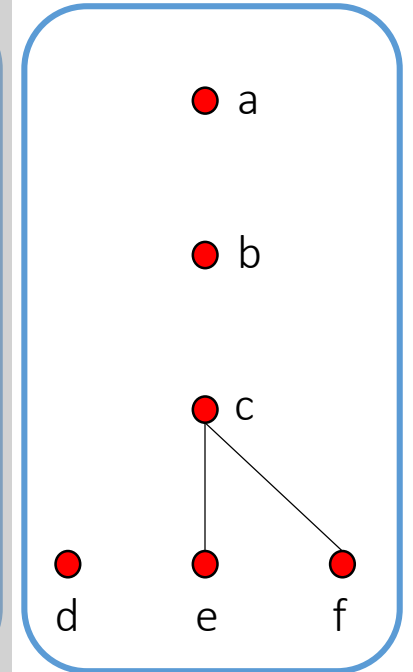
$t=3$



$t=4$



$t=5$



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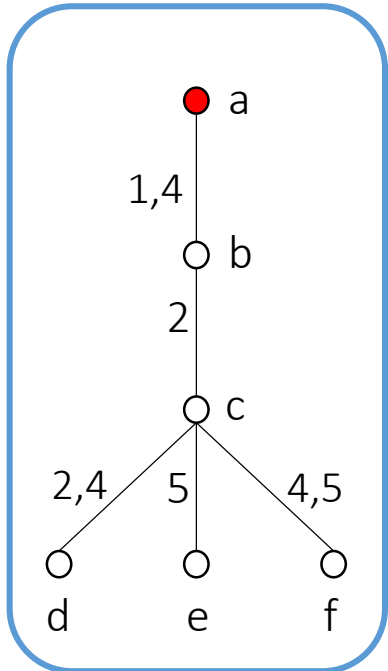
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Reachability set of  $v$ : Set of reachable vertices from  $v$

Epidemiology

Restrict spread infection

$S = \{a\}$





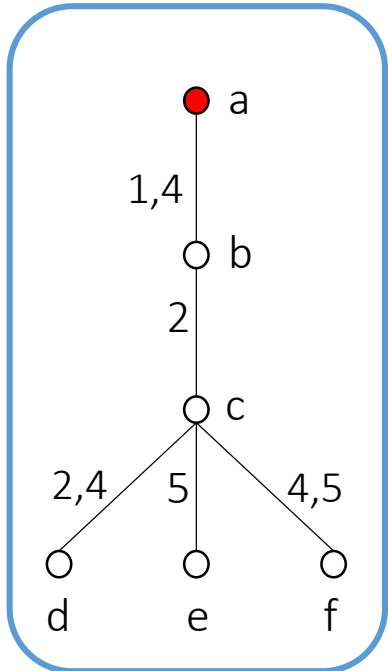
# Reachability sets in temporal graphs

- Graph  $G = (V, E)$
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How to optimize the reachability set in a temporal graph?

Epidemiology  
Restrict spread infection

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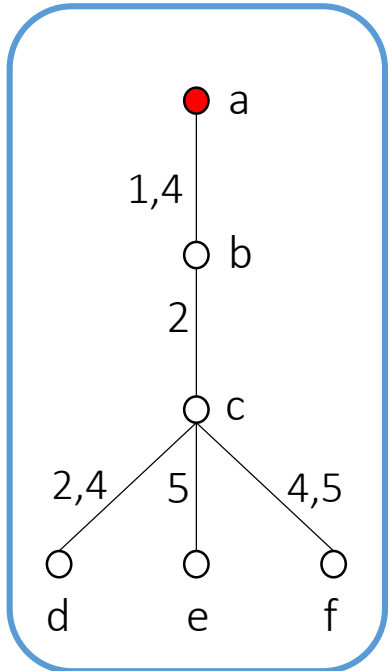
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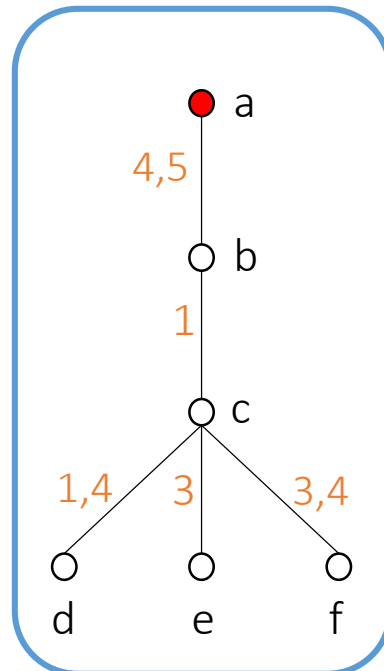
How to optimize the reachability set in a temporal graph?

Approach 1: Reshuffling  
Enright, Meeks

$S = \{a\}$



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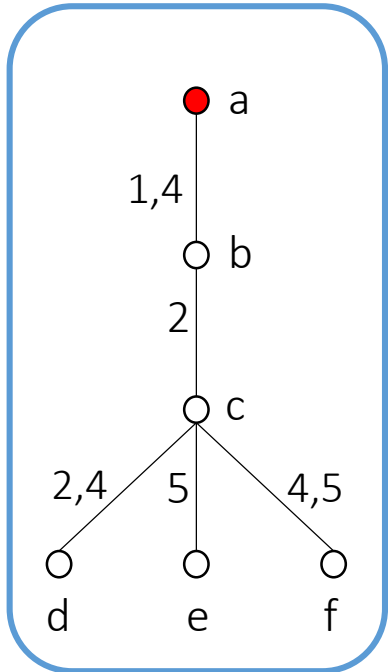
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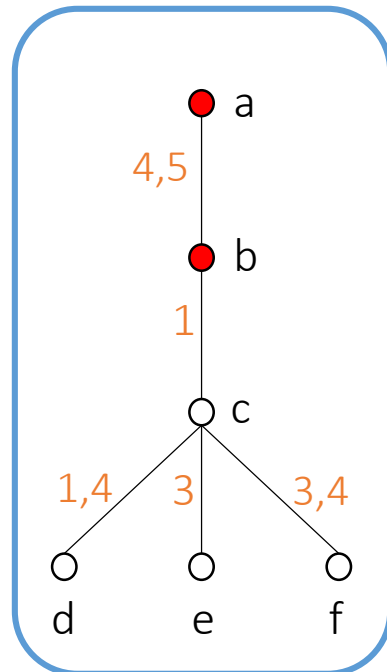
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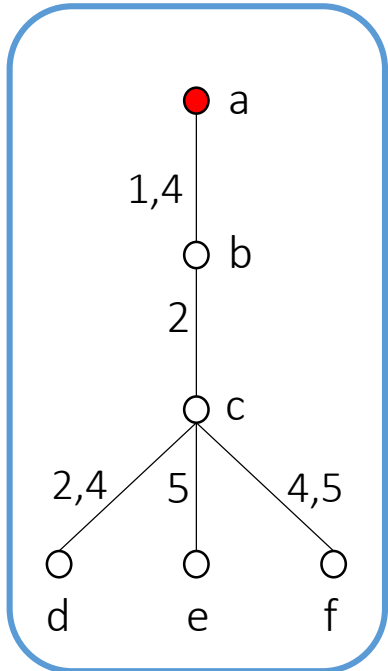
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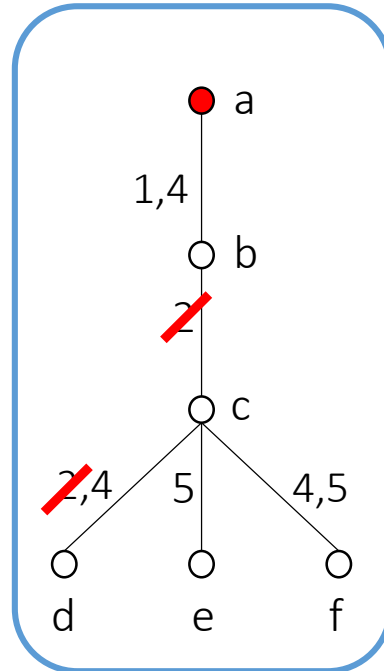
Approach 2: Edge deletion  
Enright, Meeks, Mertzios,  
Zamaraev

Delete all edges with label 2

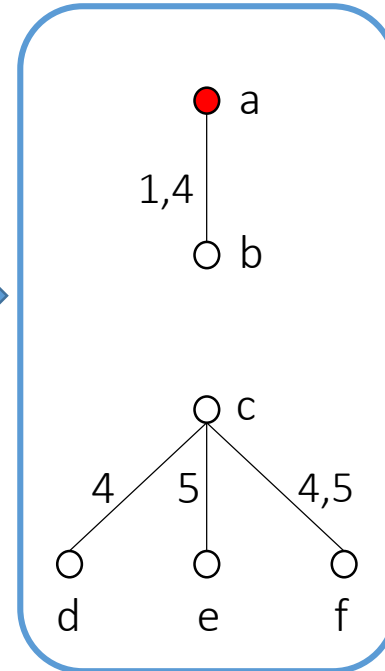
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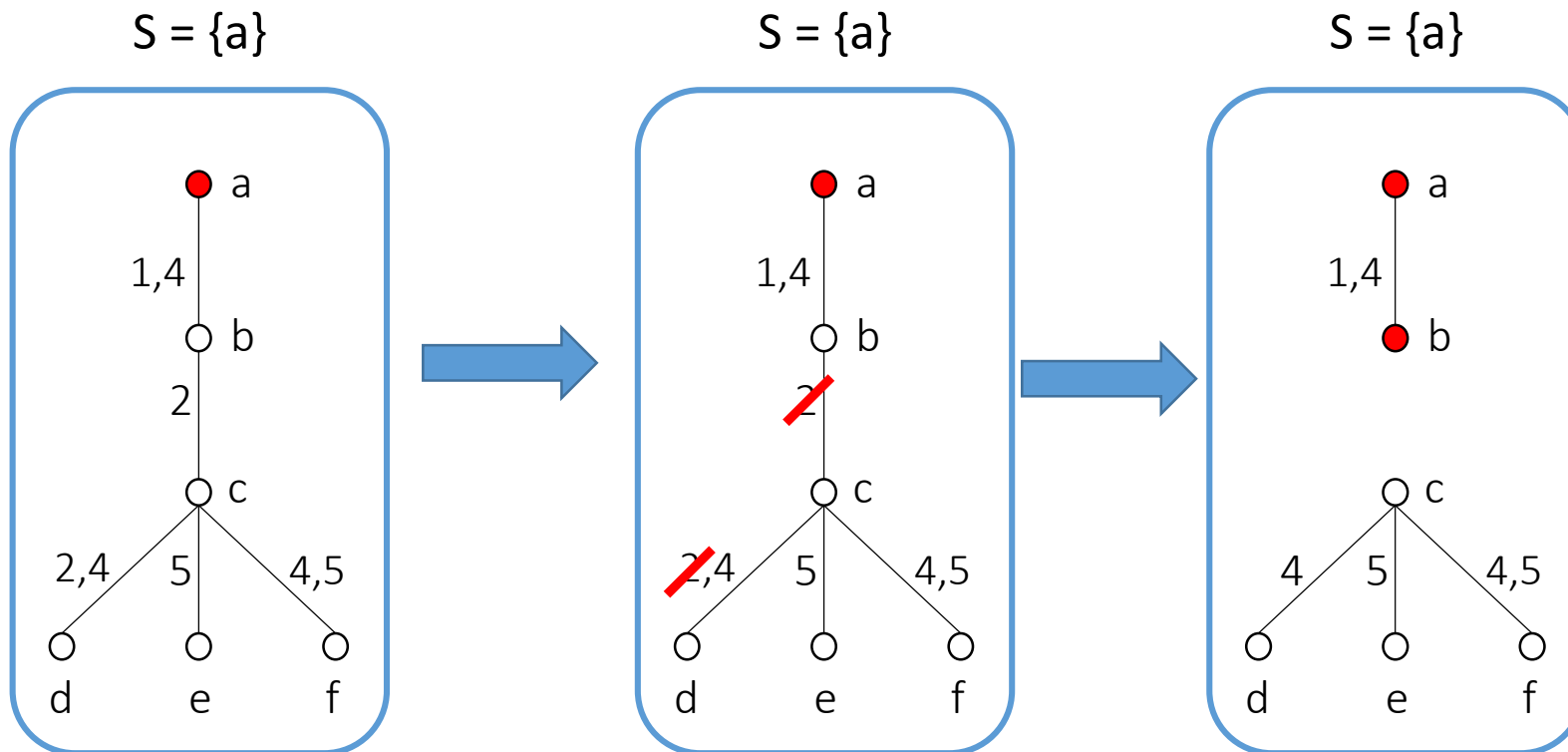
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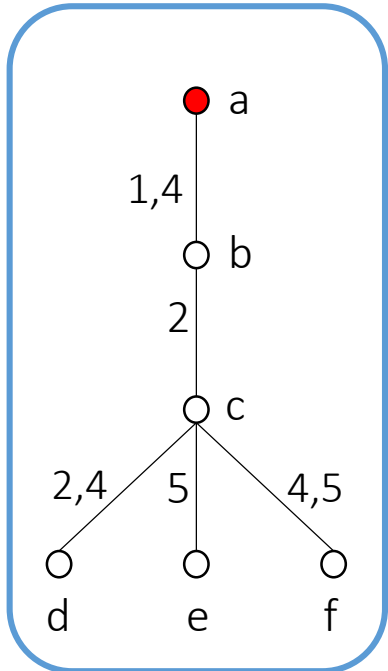
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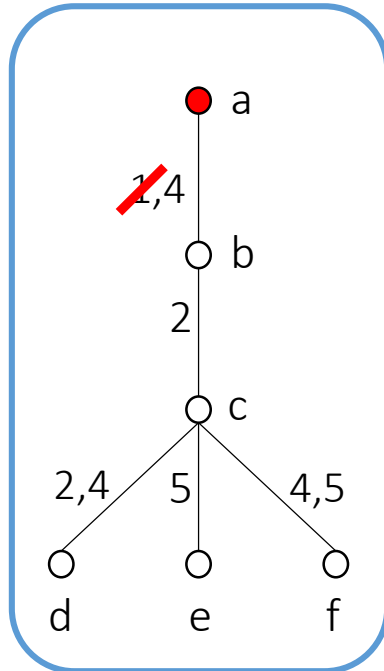
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Delete label 1 from edge ab

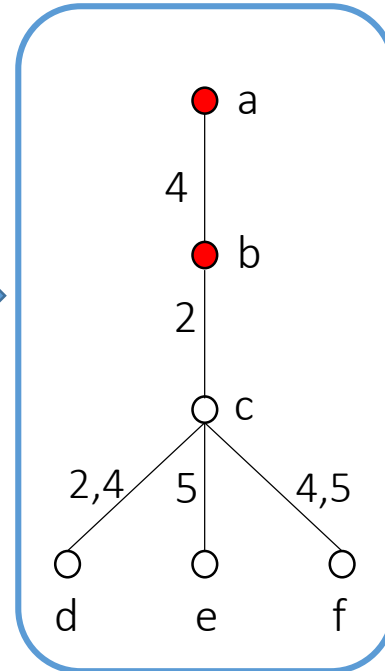
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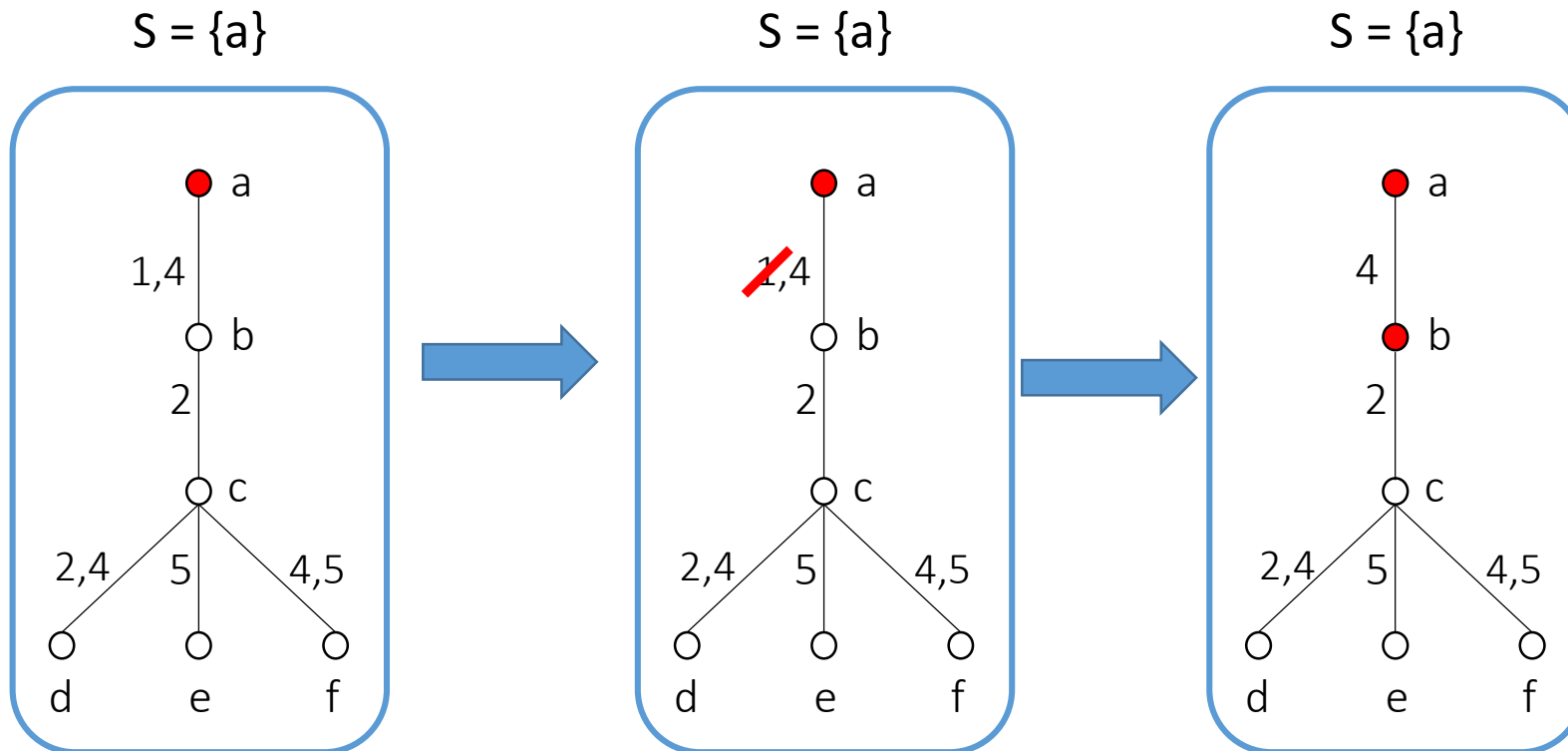
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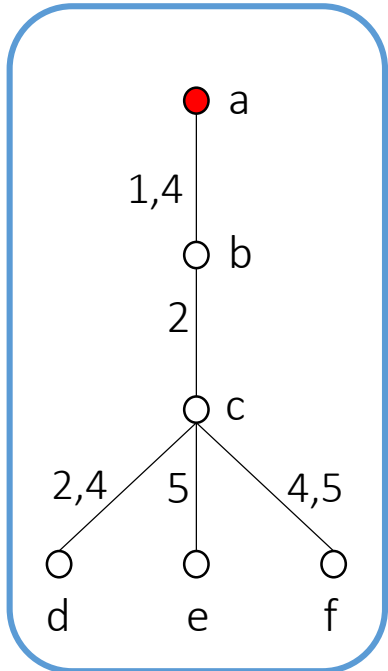
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How to optimize the reachability set in a temporal graph?

Approach 1: Reshuffling  
Enright, Meeks

**Not always possible  
in real-life networks**  
(too many changes)

Approach 2: Edge deletion  
Enright, Meeks, Mertzios,  
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**Can create deadends  
in the network**  
(blocks the flow)

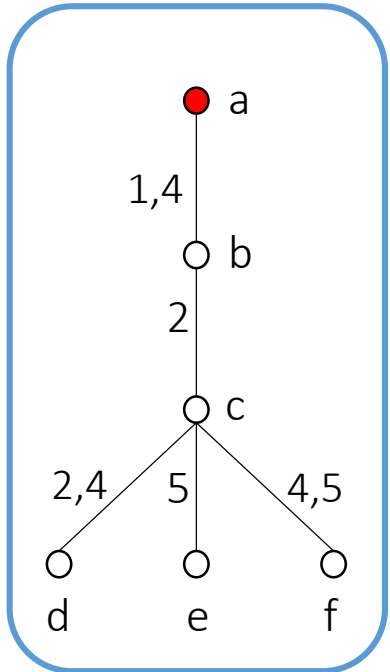


# Our approach: Delaying

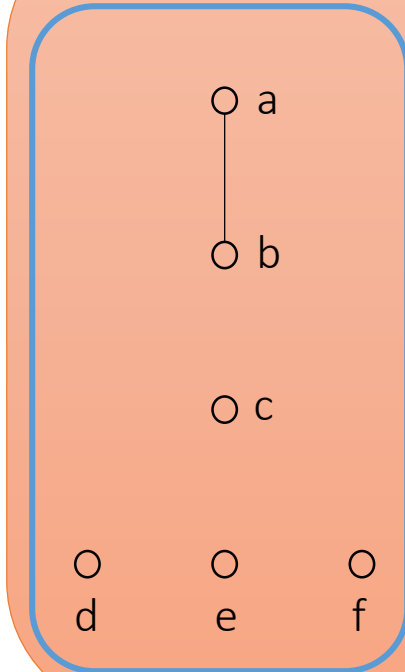
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Merging operation

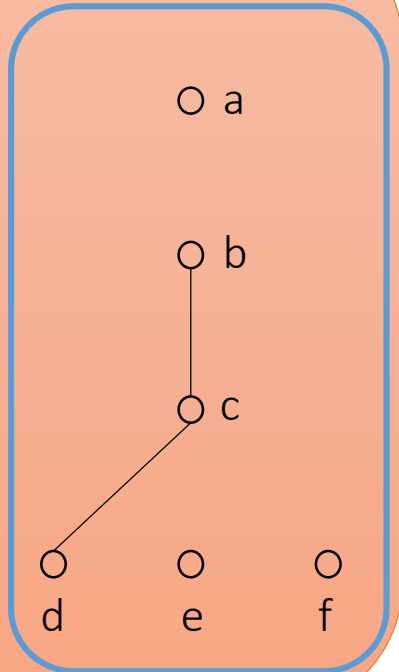
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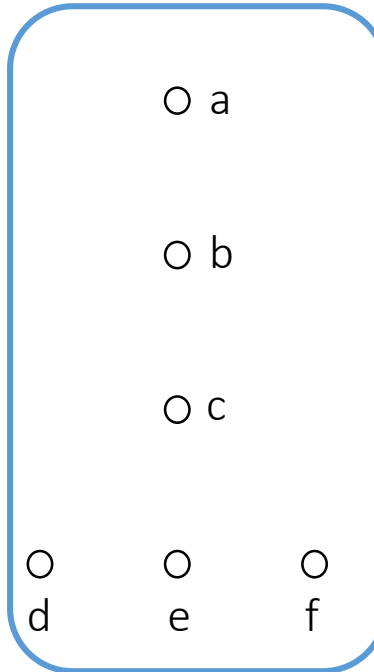
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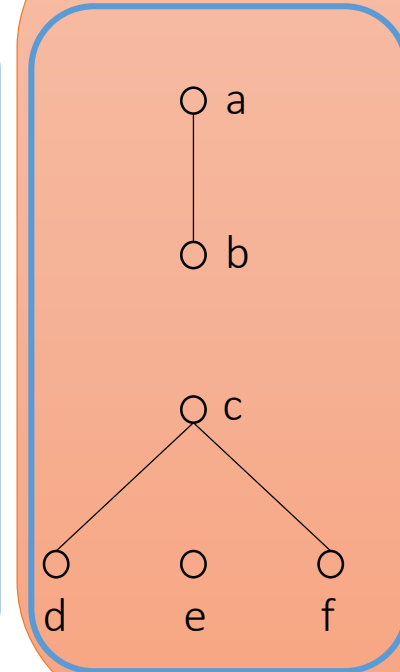
$t=2$



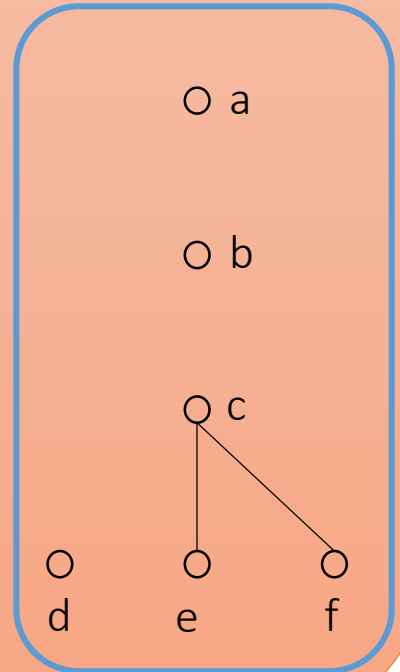
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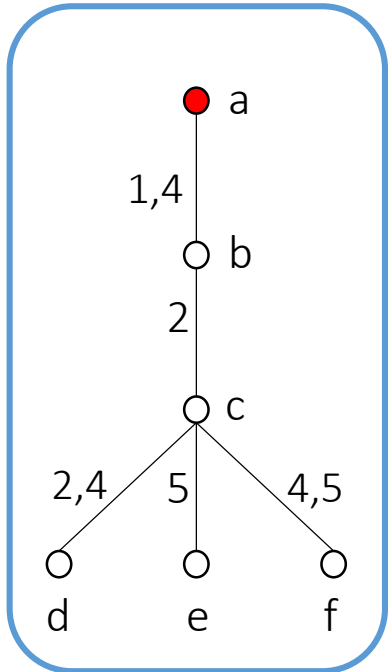
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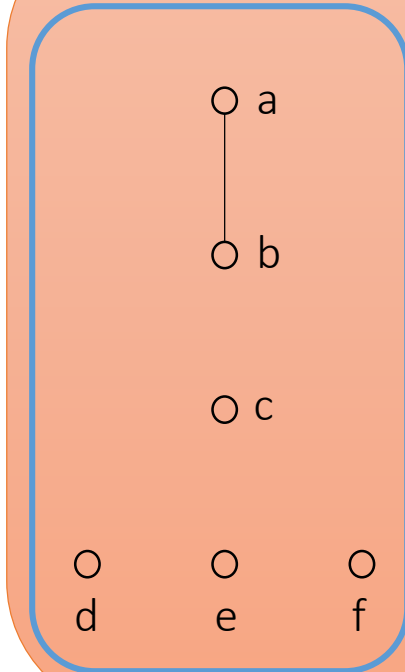
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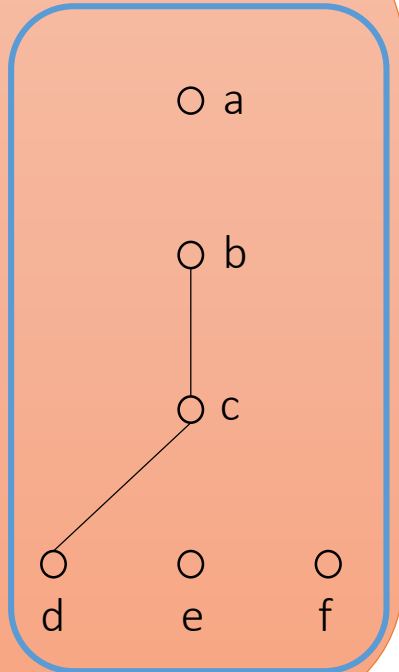
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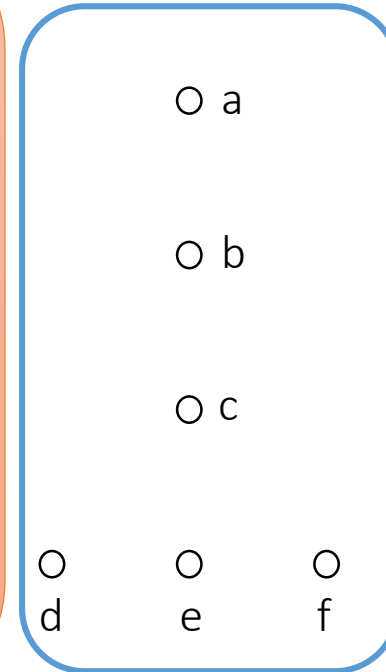
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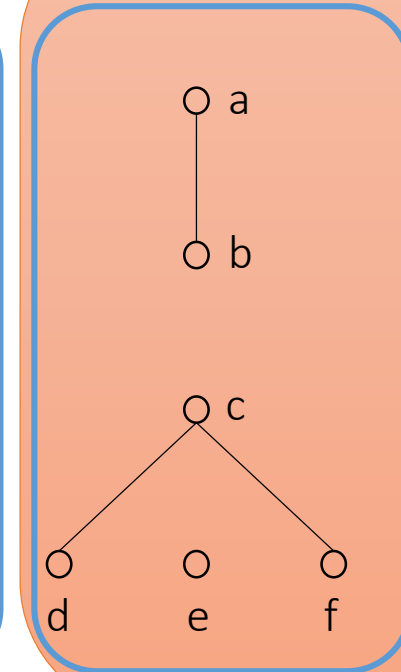
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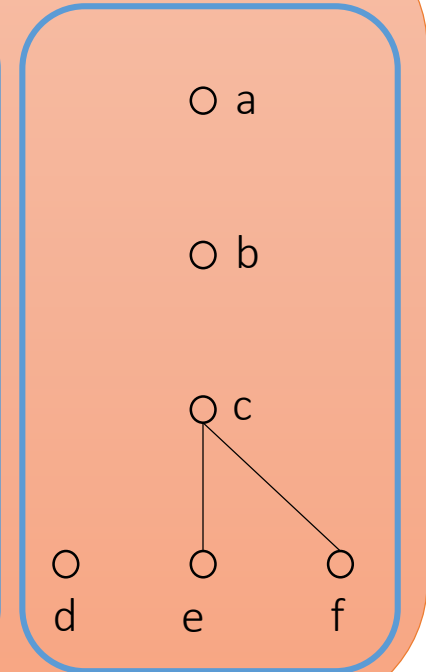
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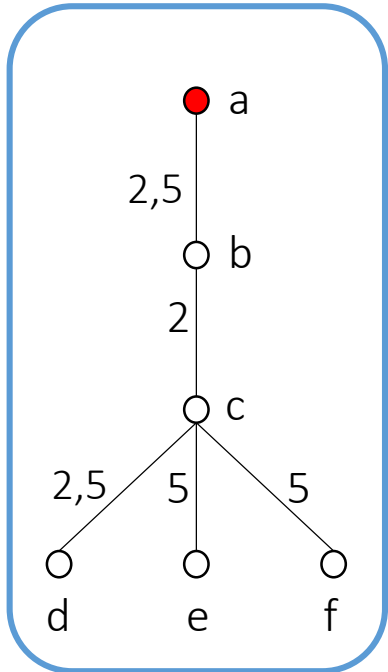
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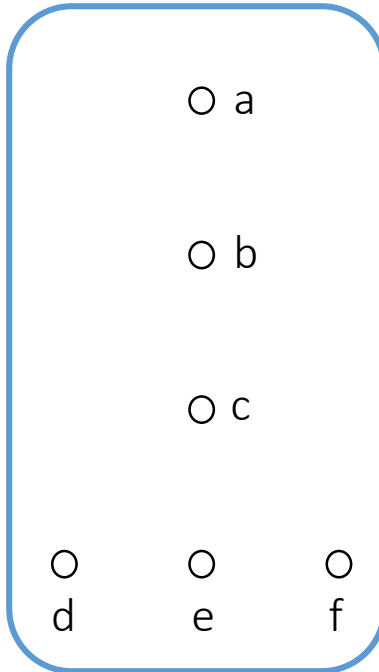
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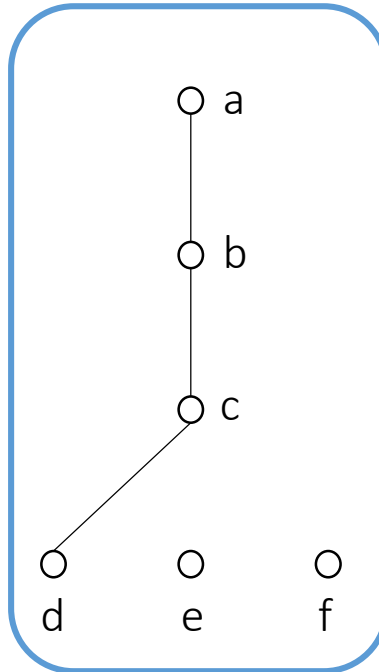
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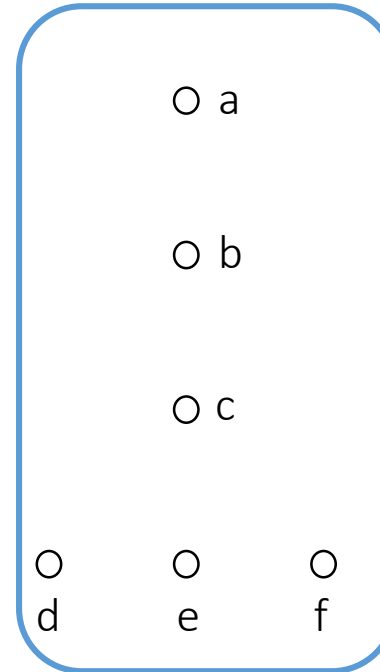
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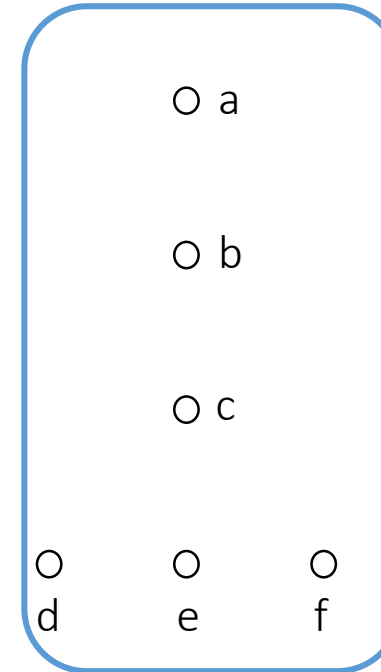
t=2



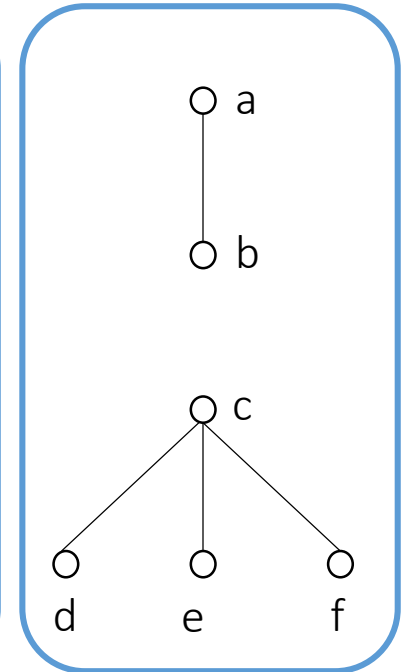
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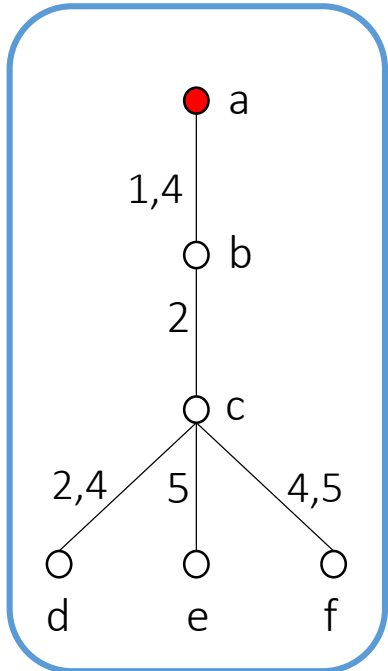
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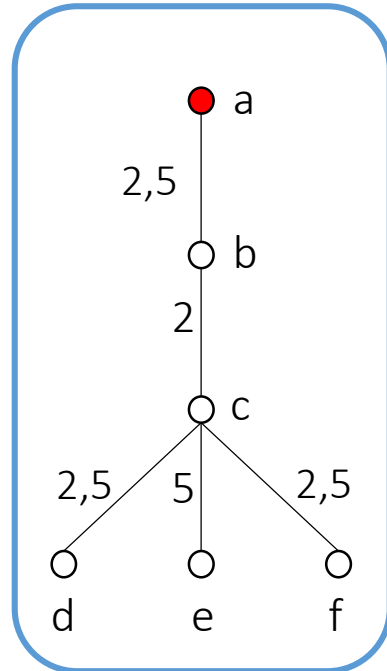
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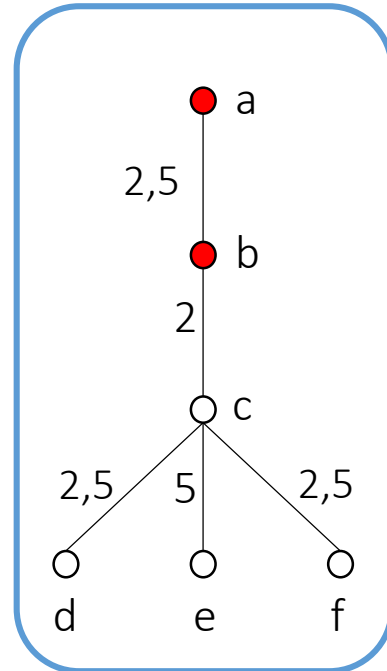
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- Minimum modification/disturbance of the original network
- Does not create deadends
- Intuitive

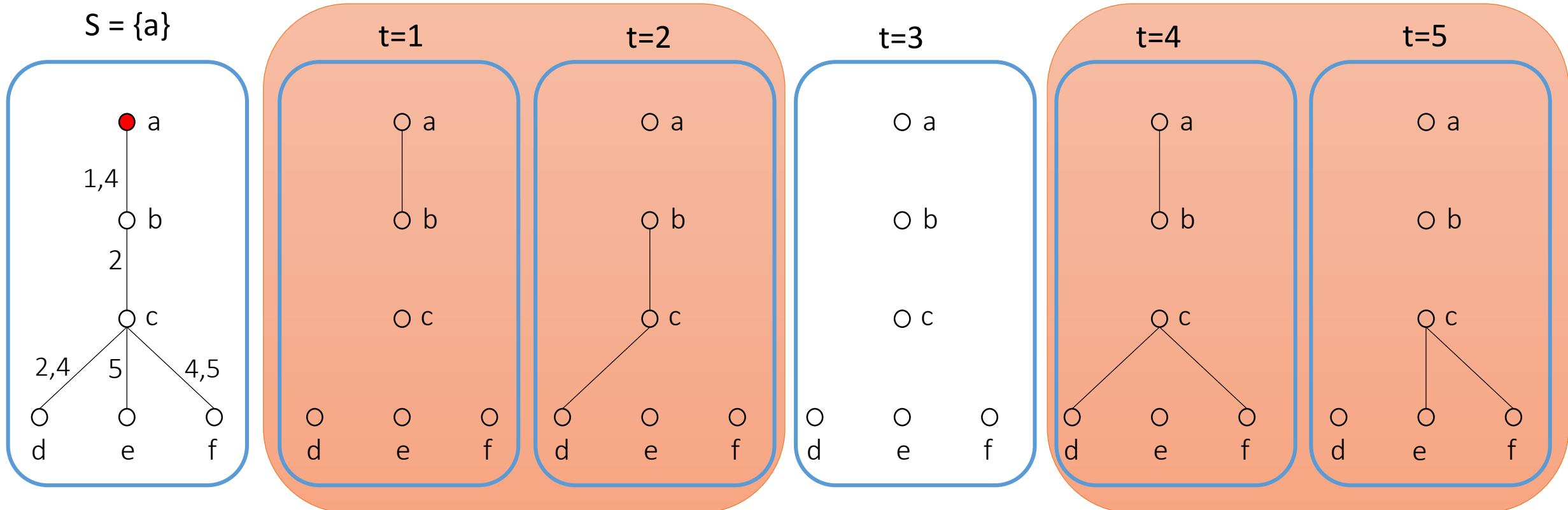
# Merging Schemes

A  $(\lambda, \mu)$ -merging scheme uses at most/least  $\mu$  **independent**  $\lambda$ -merges

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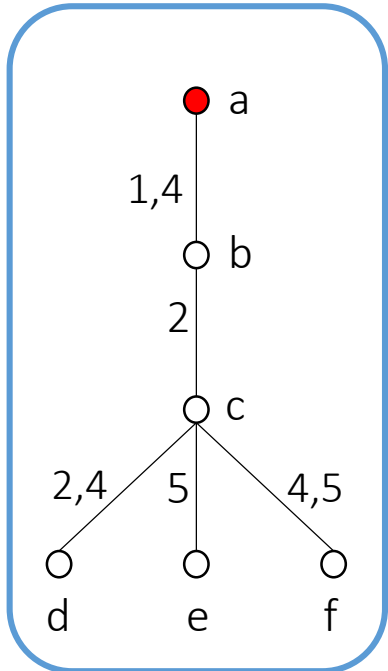
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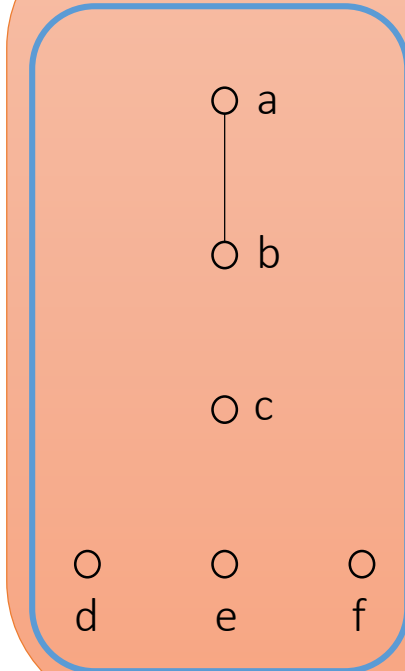
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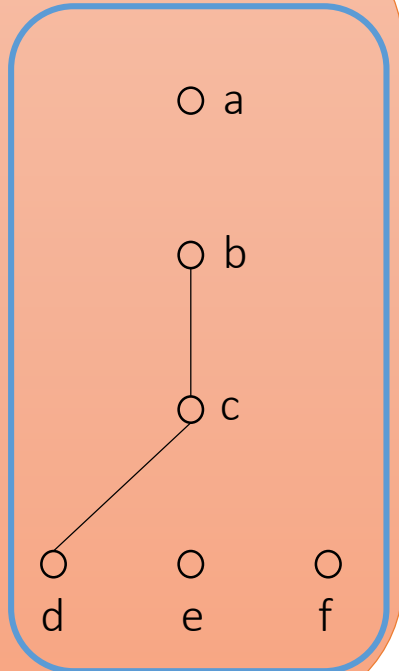
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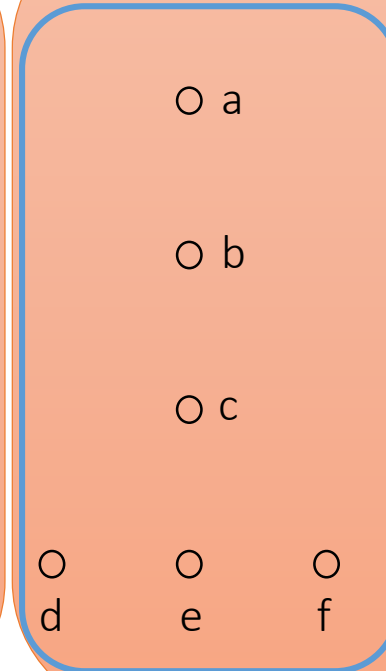
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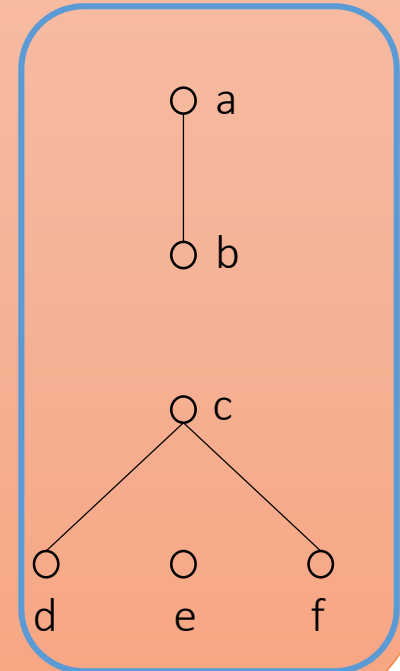
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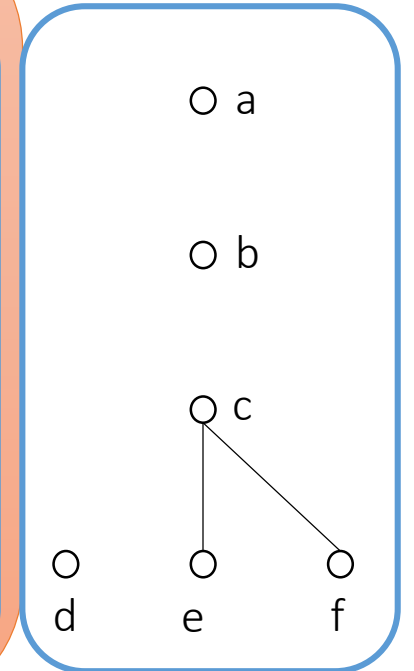
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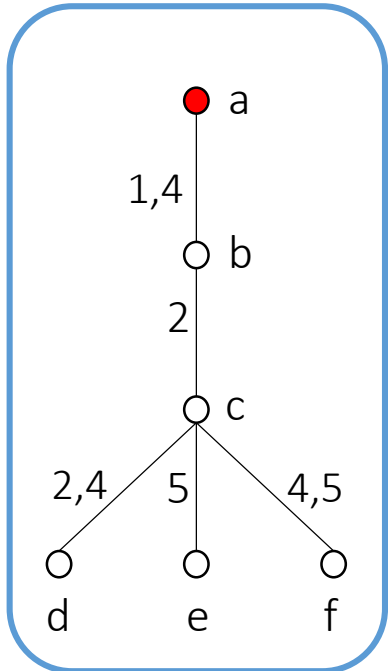
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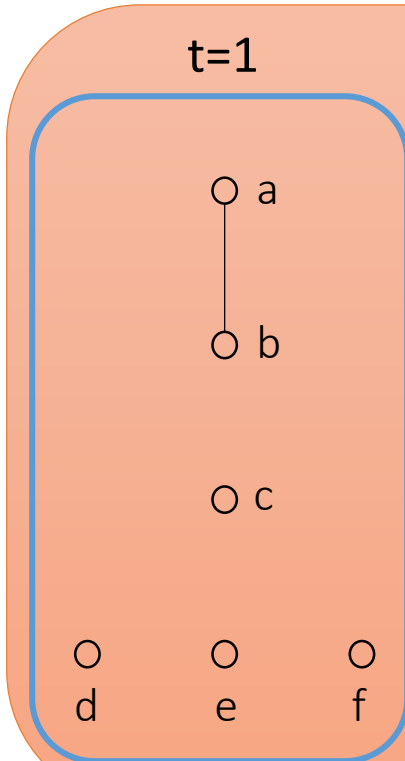
$E_{i+\lambda-1} = E_i \cup \dots \cup E_{i+\lambda-1}$

Not independent

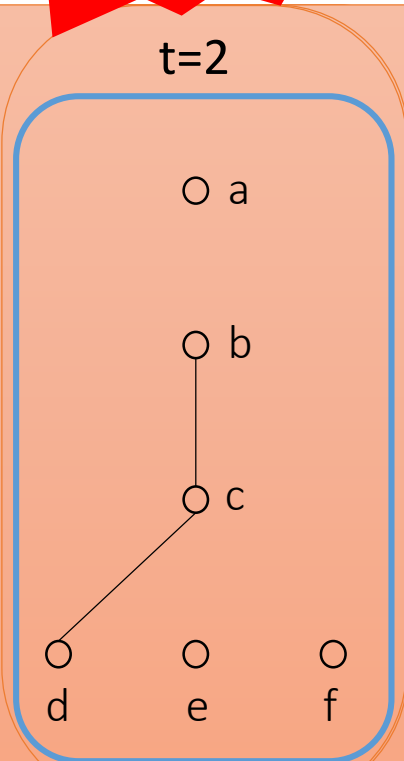
$S = \{a\}$



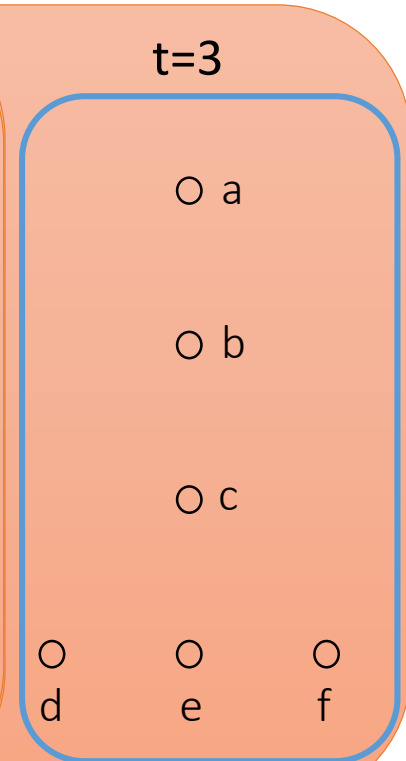
t=1



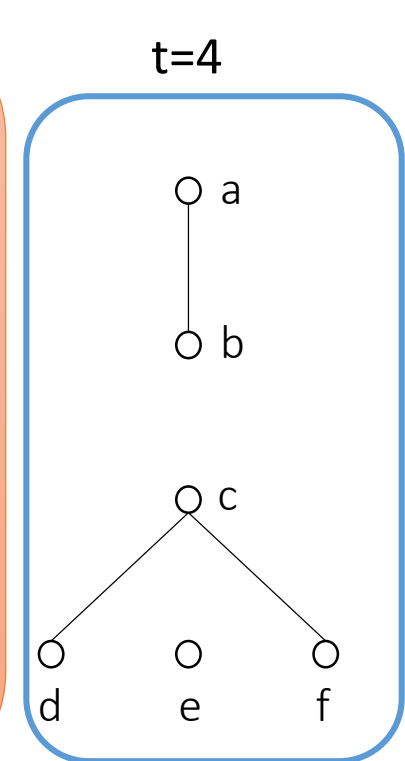
t=2



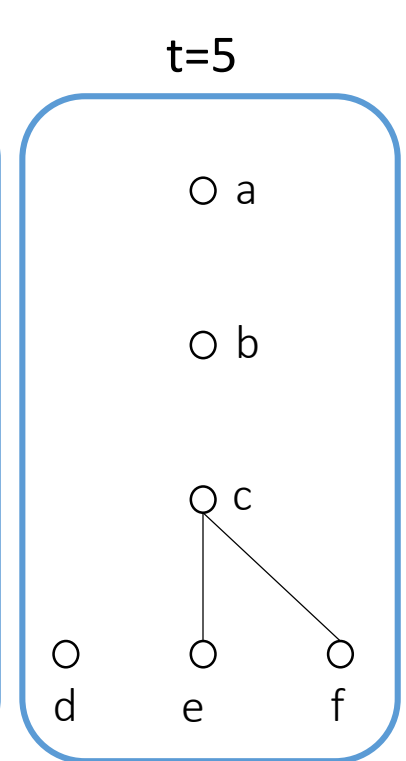
t=3



t=4



t=5



# Merging Schemes: Objectives

A  $(\lambda, \mu)$ -merging scheme uses at most/least  $\mu$  **independent**  $\lambda$ -merges

## Input

- Temporal graph  $\langle G, T \rangle$
- Integers  $\lambda$  and  $\mu$
- Set of sources  $S$

$\lambda$ -merge:  $E_i, \dots, E_{i+\lambda-1}$

$$E_i = \dots = E_{i+\lambda-2} = \emptyset$$

$$E_{i+\lambda-1} = E_i \cup \dots \cup E_{i+\lambda-1}$$



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## Minimization Objectives

$(\lambda, \mu)$ -merging scheme uses **at most**  $\mu$  independent  $\lambda$ -merges

➤ MinReach:  $\min |\cup_{v \in S} reach(v, \langle G, T \rangle)|$

➤ MinMaxReach:  $\min \max_{v \in S} |reach(v, \langle G, T \rangle)|$

➤ MinAvgReach:  $\min \sum_{v \in S} |reach(v, \langle G, T \rangle)|$

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- Temporal graph  $\langle G, T \rangle$
- Integers  $\lambda$  and  $\mu$
- Set of sources  $S$

When  $|S| = 1$ , all problems coincide

## Minimization Objectives

$(\lambda, \mu)$ -merging scheme uses **at most**  $\mu$  independent  $\lambda$ -merges

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## Maximization Objectives

$(\lambda, \mu)$ -merging scheme uses **at least**  $\mu$  independent  $\lambda$ -merges

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# Our Results

Problem	Graph	# Sources	# Labels/Edge	# Edges/Step
MinReach	Path	$O(n)$	1	3
MinReach MinMaxReach MinAvgReach	Tree max degree 3	1	1	1
MaxReach	Path	$O(n)$	1	4
MaxReach MaxMinReach MaxAvgReach	Bipartite Max degree 3	1	1	4
MaxReach MaxMinReach MaxAvgReach	Tree max degree 3	1	1	10

NP-hard for every  $\lambda$

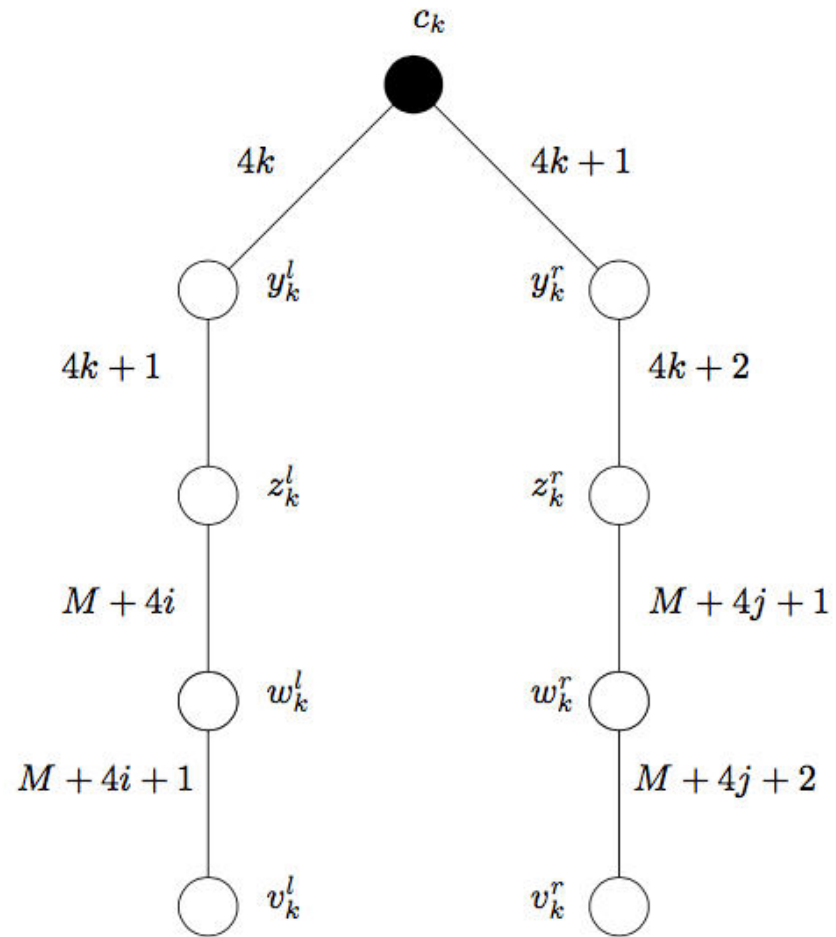
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MaxReach MaxMinReach MaxAvgReach	Bipartite Max degree 3	1	1	4
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NP-hard for every  $\lambda$

- **DAGs**
- **Unit disk graphs**
- **Approximation preserving, no PTAS**

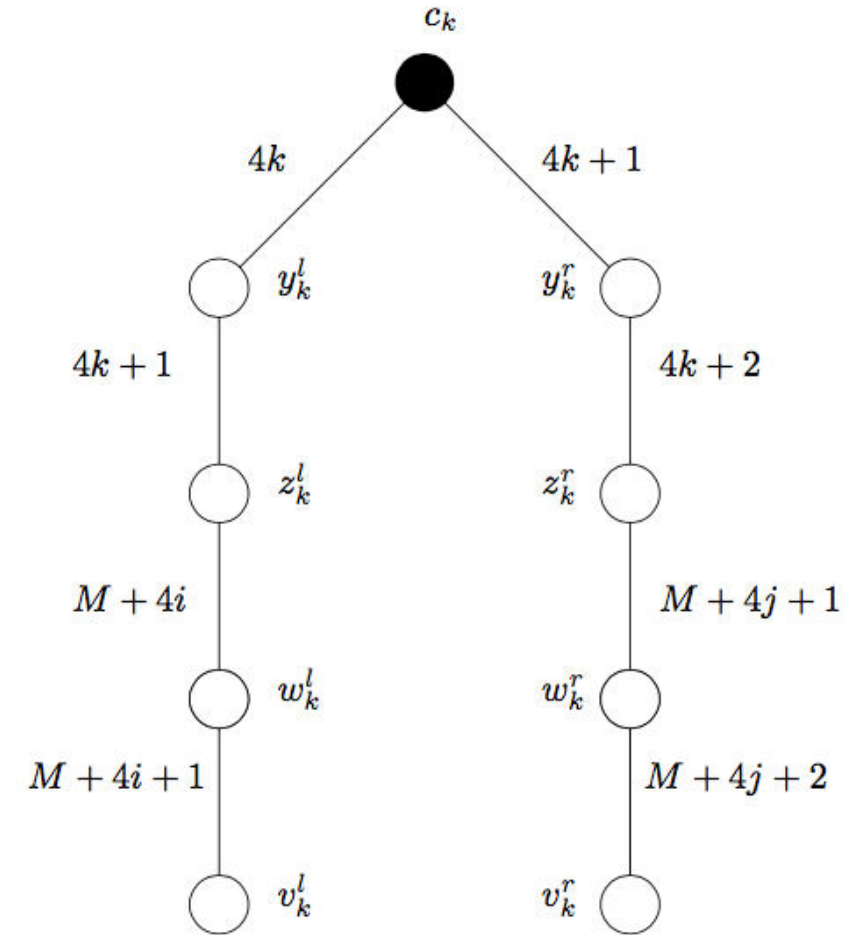
# Idea



Reduction from Max2SAT(3)

# Open Questions

- Approximation Algorithms
- Tractable Cases/Graph Classes
- FPT algorithms





Thanks!!

